

Mesures cinématiques et dynamiques en production de la parole

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Plan

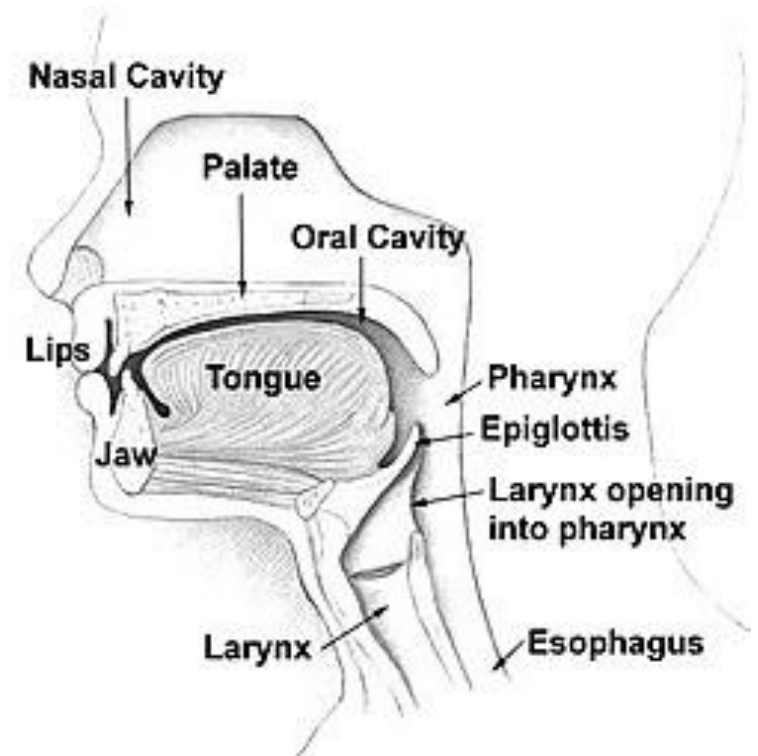
- **Présentation des enjeux**
- **Mesure des mouvements des articulateurs non visibles**
 - **Électromagnétométrie -EMA**
 - **Echographie - Ultrasound**
 - **Endoscopie & Transillumination**
 - **Electroglottographie -EGG**
 - **Electropalatographie -EPG**
- **Mesures dynamiques**
 - **Capteurs de force**
 - **Electromyographie**
- **Exemples de paradigmes expérimentaux.**

Présentation des enjeux

Speech motor control

Purpose:

To know how articulatory organs are moved (descriptive) and how those articulatory organs are controlled (functional).



Présentation des enjeux

Speech motor control

Challenges:

Multiple-articulators are involved.

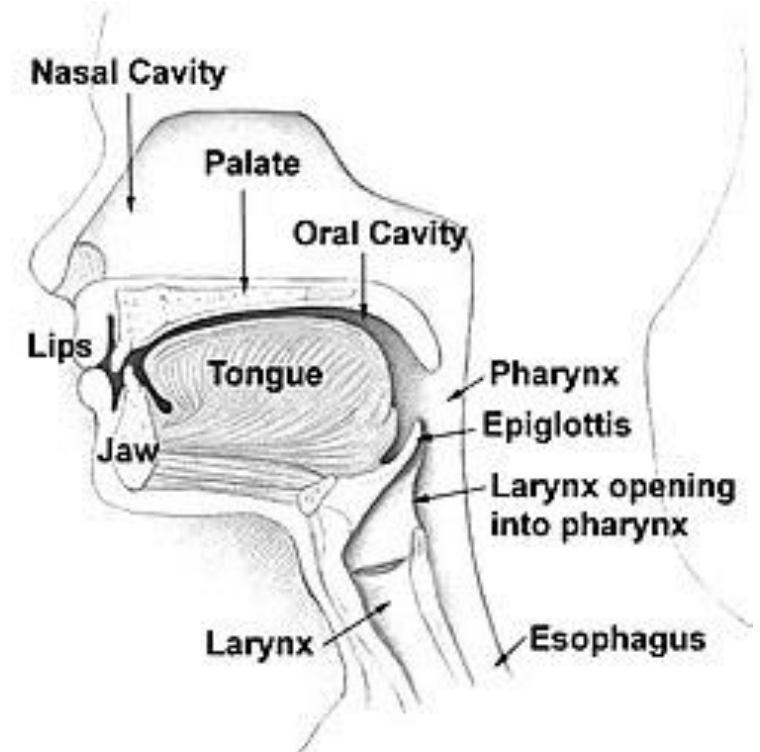
- **Required specific measurement device for each articulator**

Some of articulatory organs are difficult to observe from the outside.

- **Measurement device specific for interior organe**

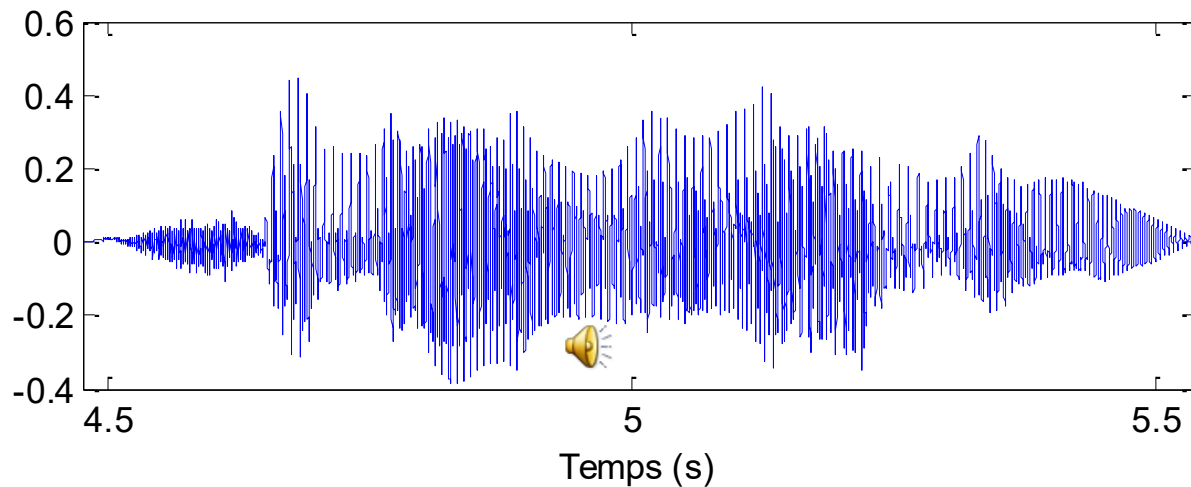
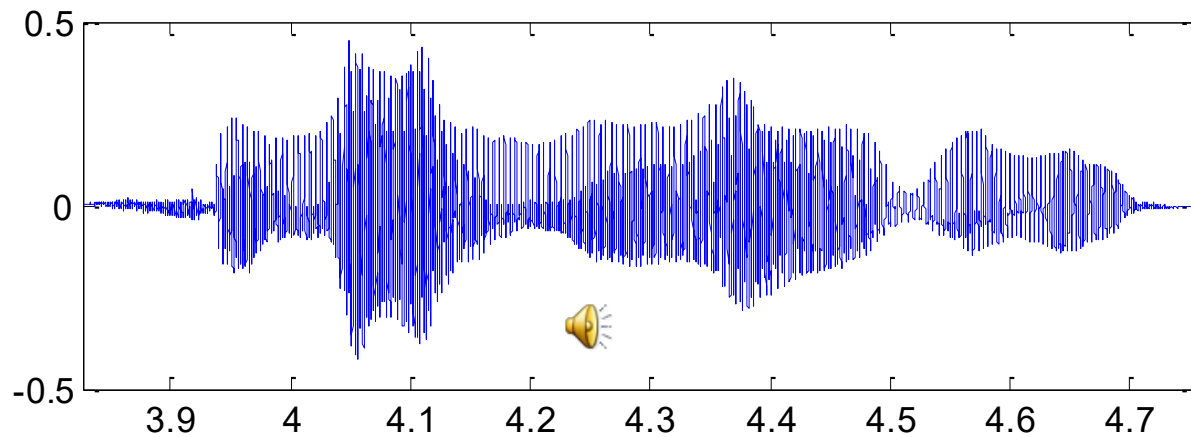
Each organ and movement are relatively fast and small.

- **Not distrub speech movement**



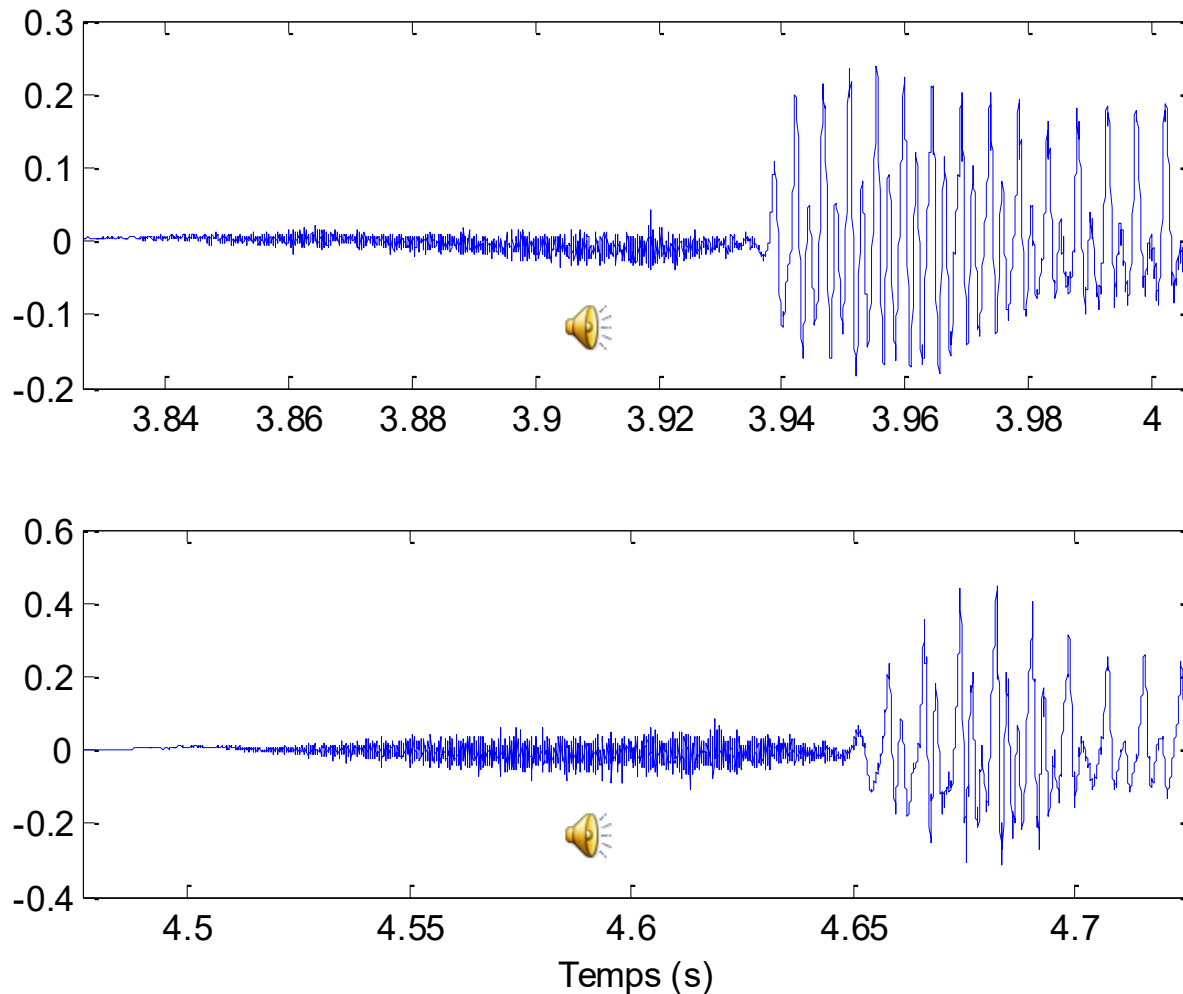
Présentation des enjeux

Le signal acoustique de la parole



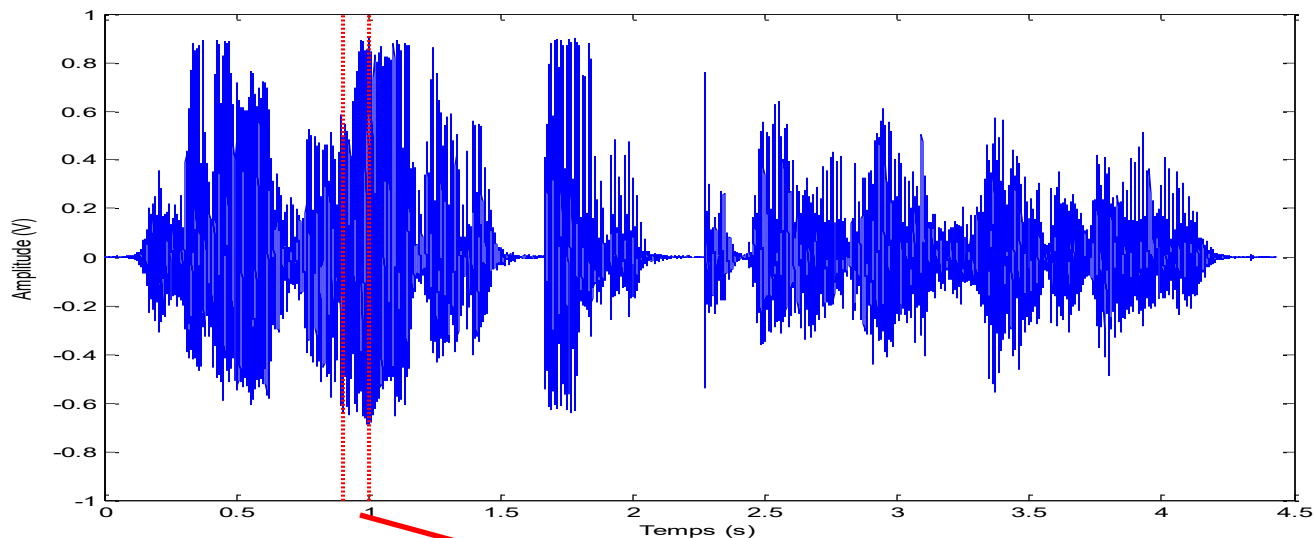
Présentation des enjeux

Le signal acoustique de la parole



Analyse à court terme

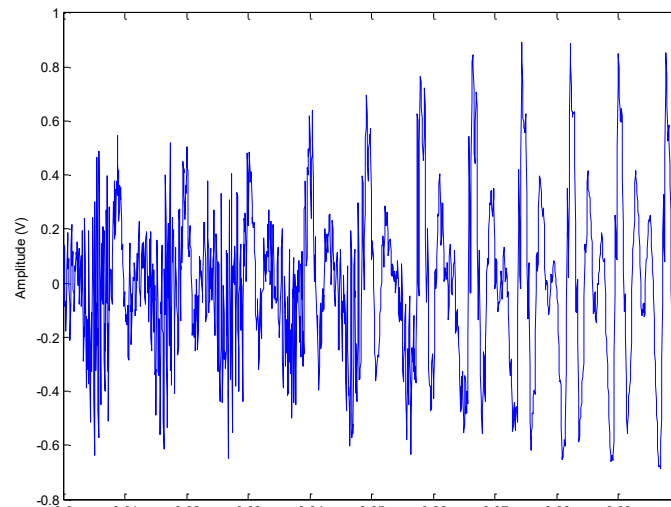
Principes



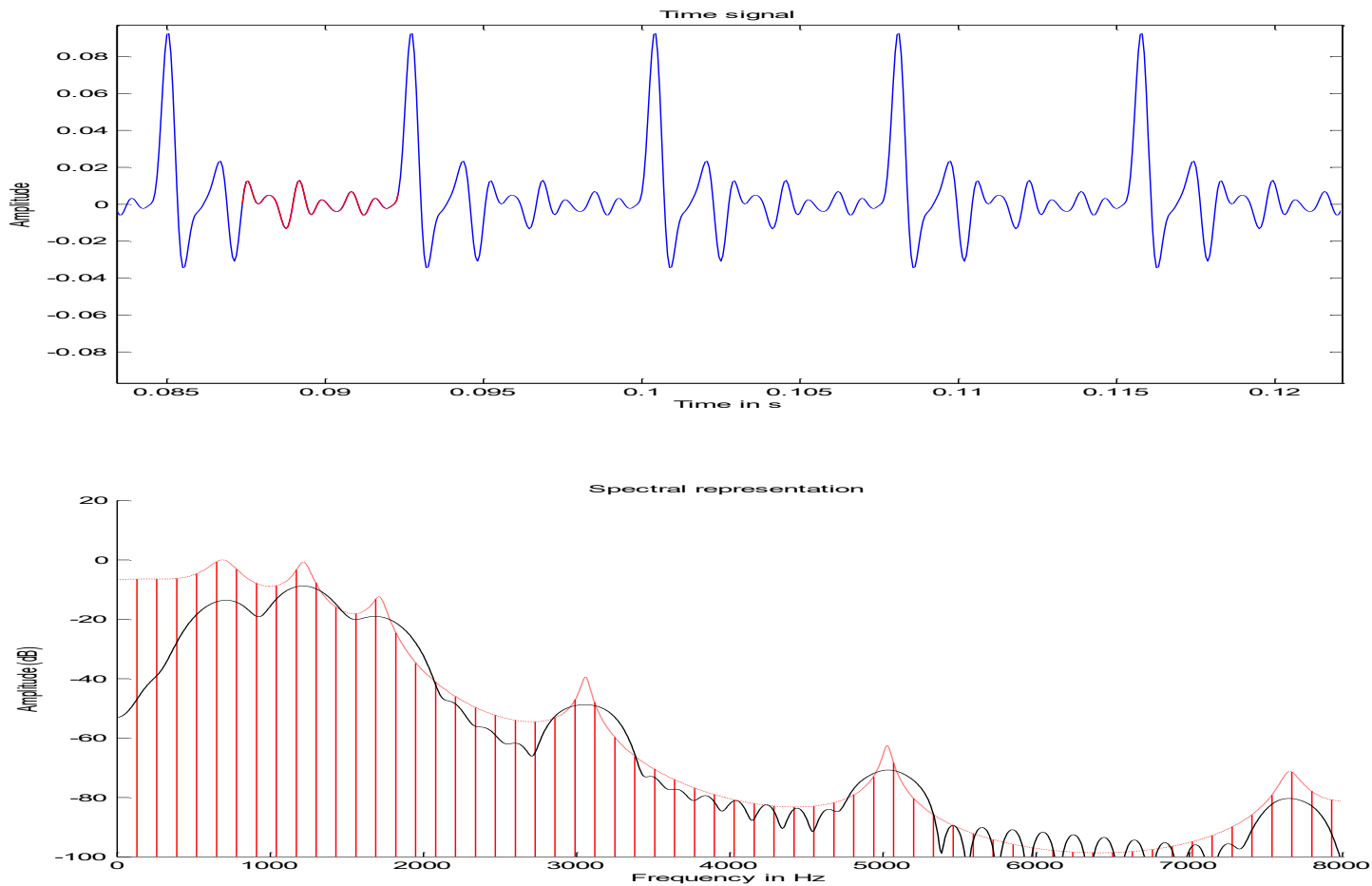
$$s_m(n) = s((m-1).N + n), \quad n \in [0, (N-1)]$$

$$s_m(n) = 0, \quad n \notin [0, (N-1)]$$

$$|S_m(f)| = |S(f) * W_N(f)|$$

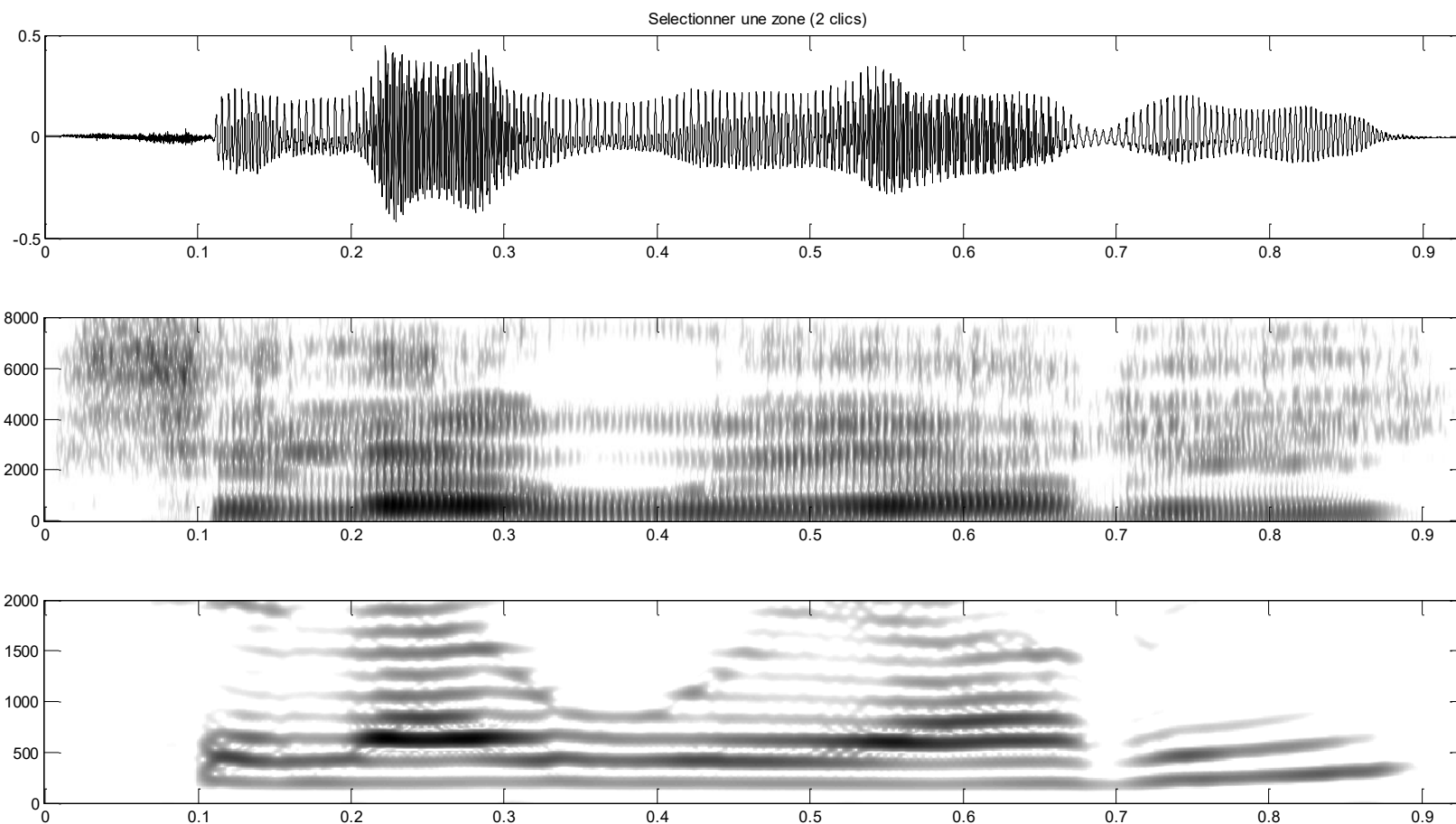


Signal de Parole



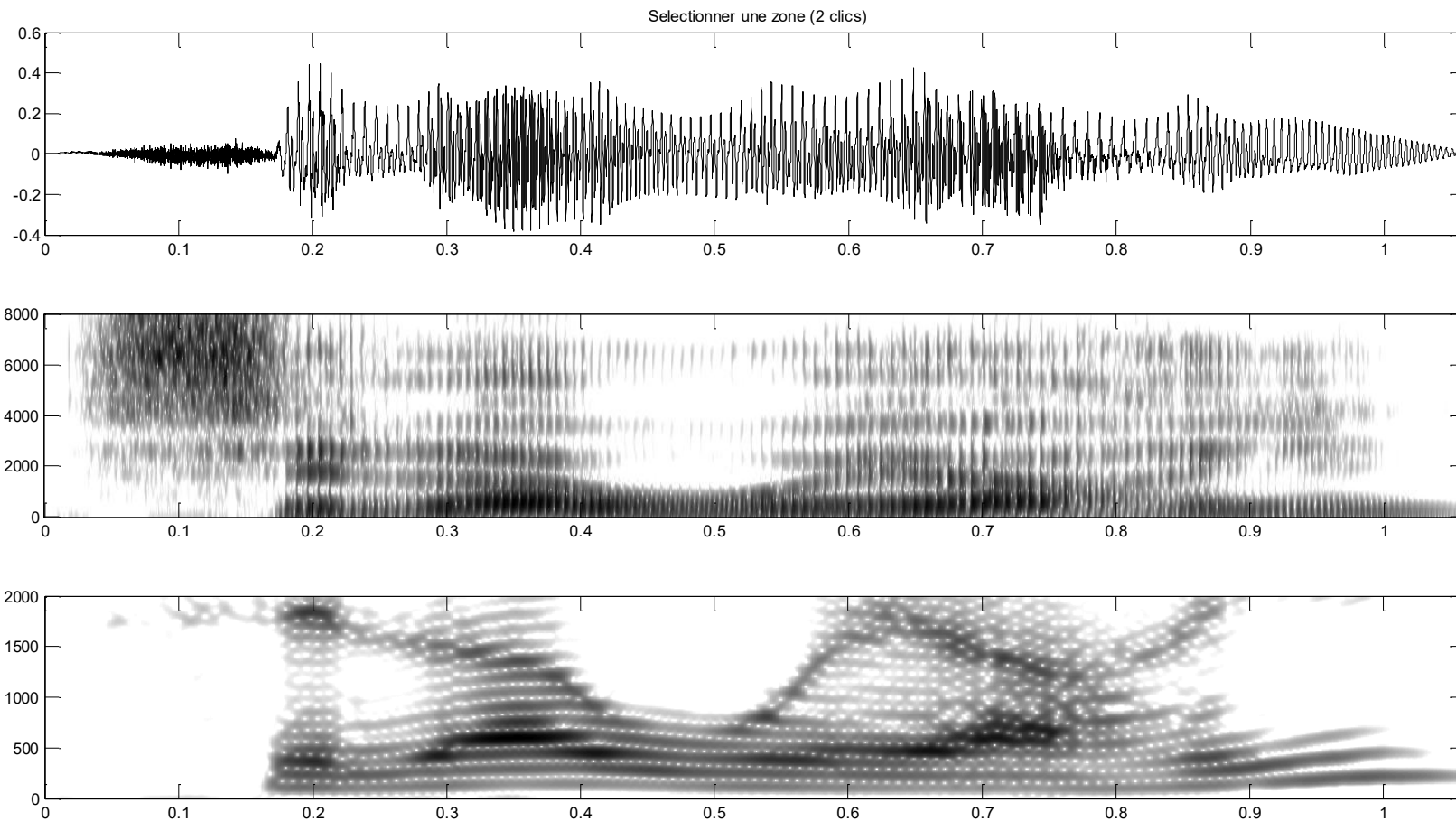
Présentation des enjeux

Le signal acoustique de la parole



Présentation des enjeux

Le signal acoustique de la parole

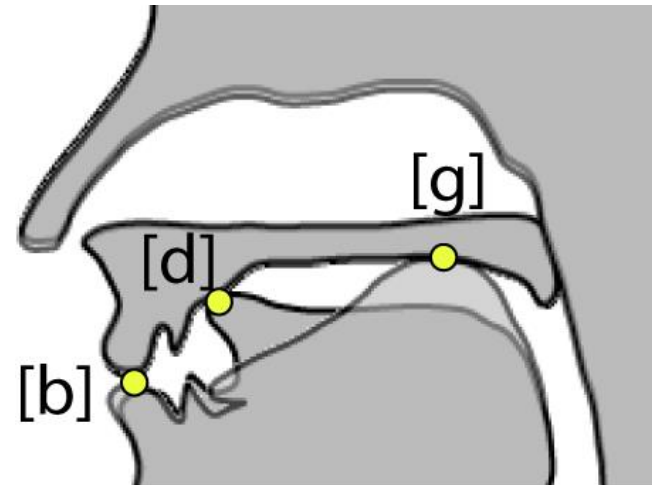


Présentation des enjeux

Produce speech sounds

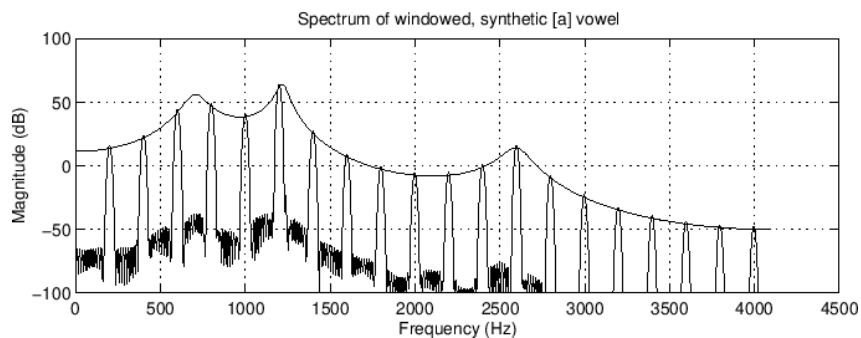
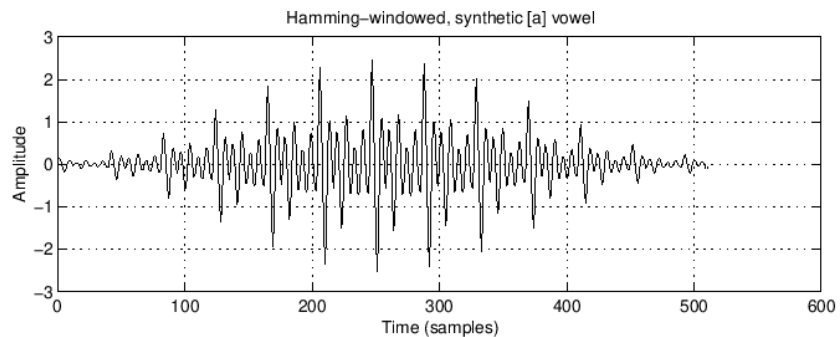
Consonant

- Place of articulation
 - Labial, alveolar, etc.
- Manner of articulation
 - Stop, Fricative, etc.
 - Voiced and unvoiced

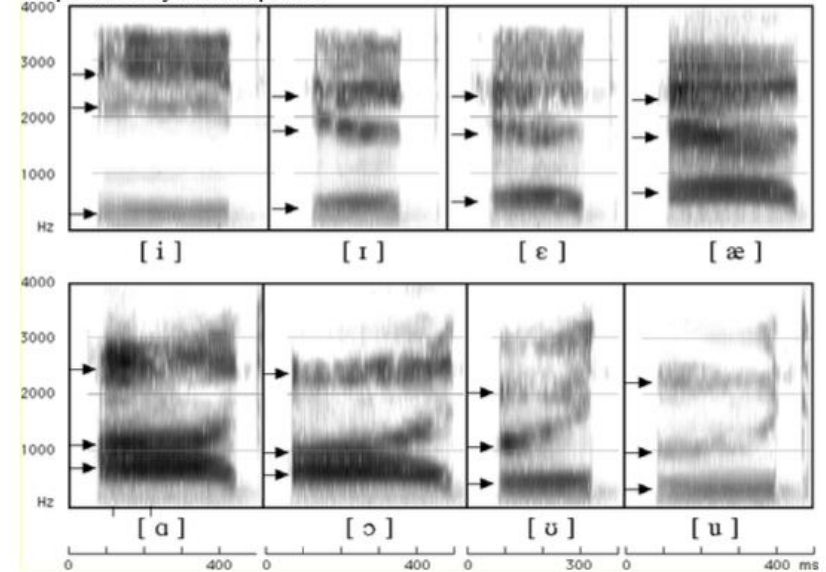


Signal de Parole

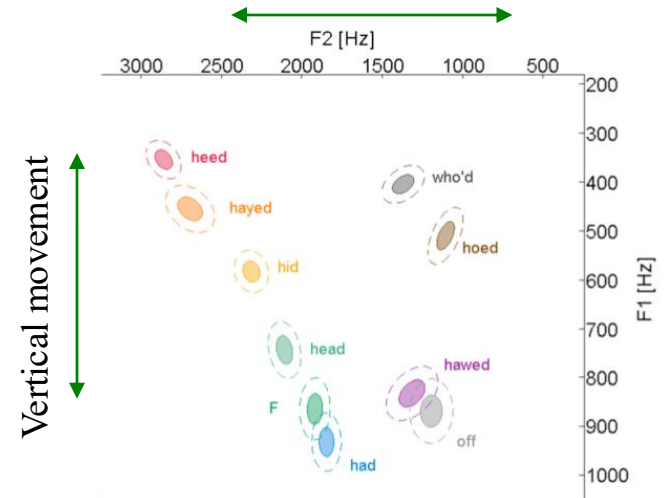
Formant



• produced by a male speaker



Horizontal movement

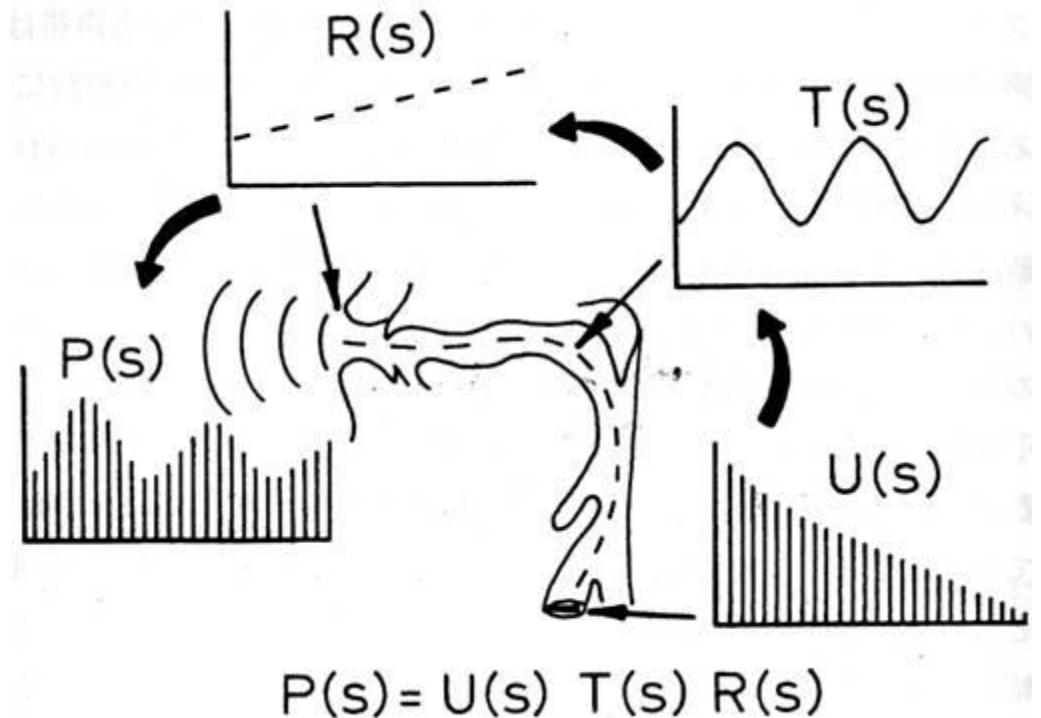


Présentation des enjeux

Produce speech sounds

Vowel

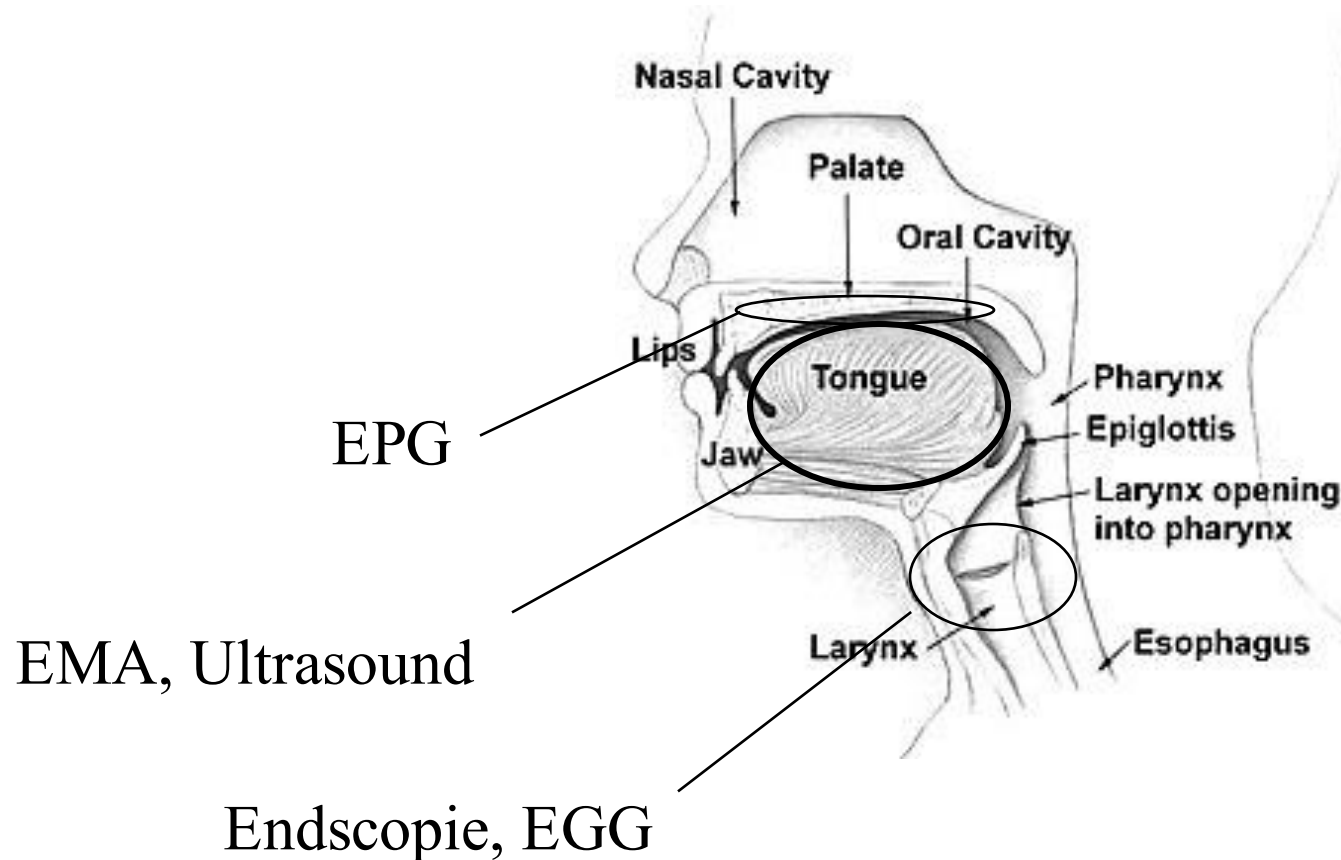
- Source-filter theory
 - Vocal tract shape



Stevens KN, 1998

Présentation des enjeux

Speech motor control



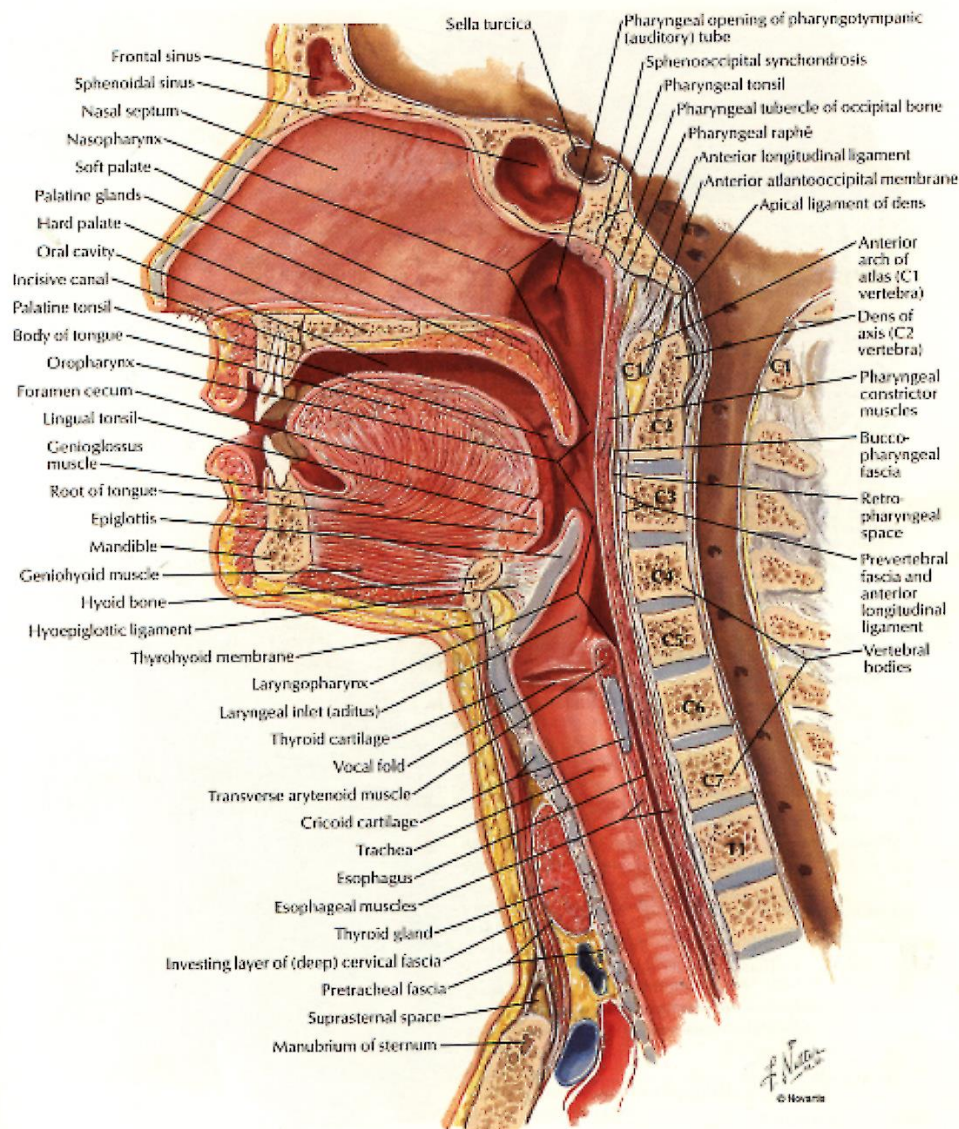
Mesures cinématiques

Anatomical basis for vocal tract

Anatomical basis

Coupe sagittale du conduit vocal

Netter (1984)
Atlas of Human Anatomy.

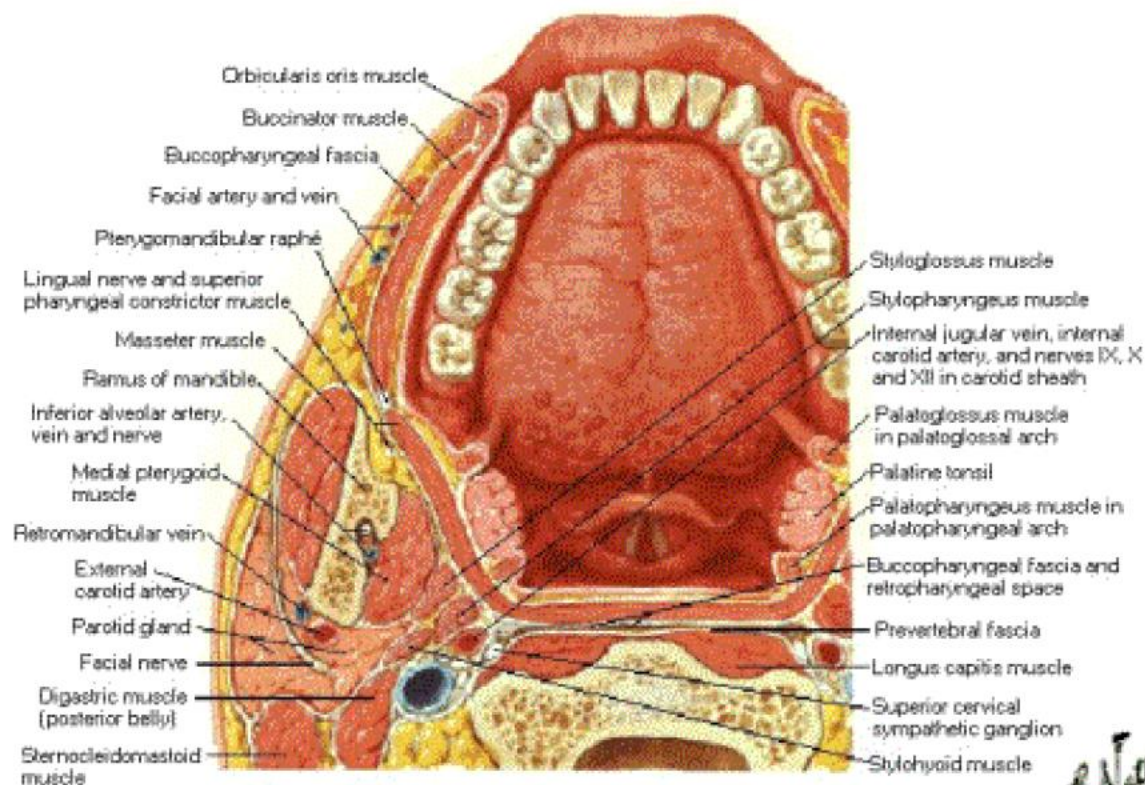


Anatomical basis

Vue de dessus

Netter (1984)
Atlas of Human Anatomy.

Tongue and Mouth
Horizontal Section - Superior View



Sectioned below lingula of mandible

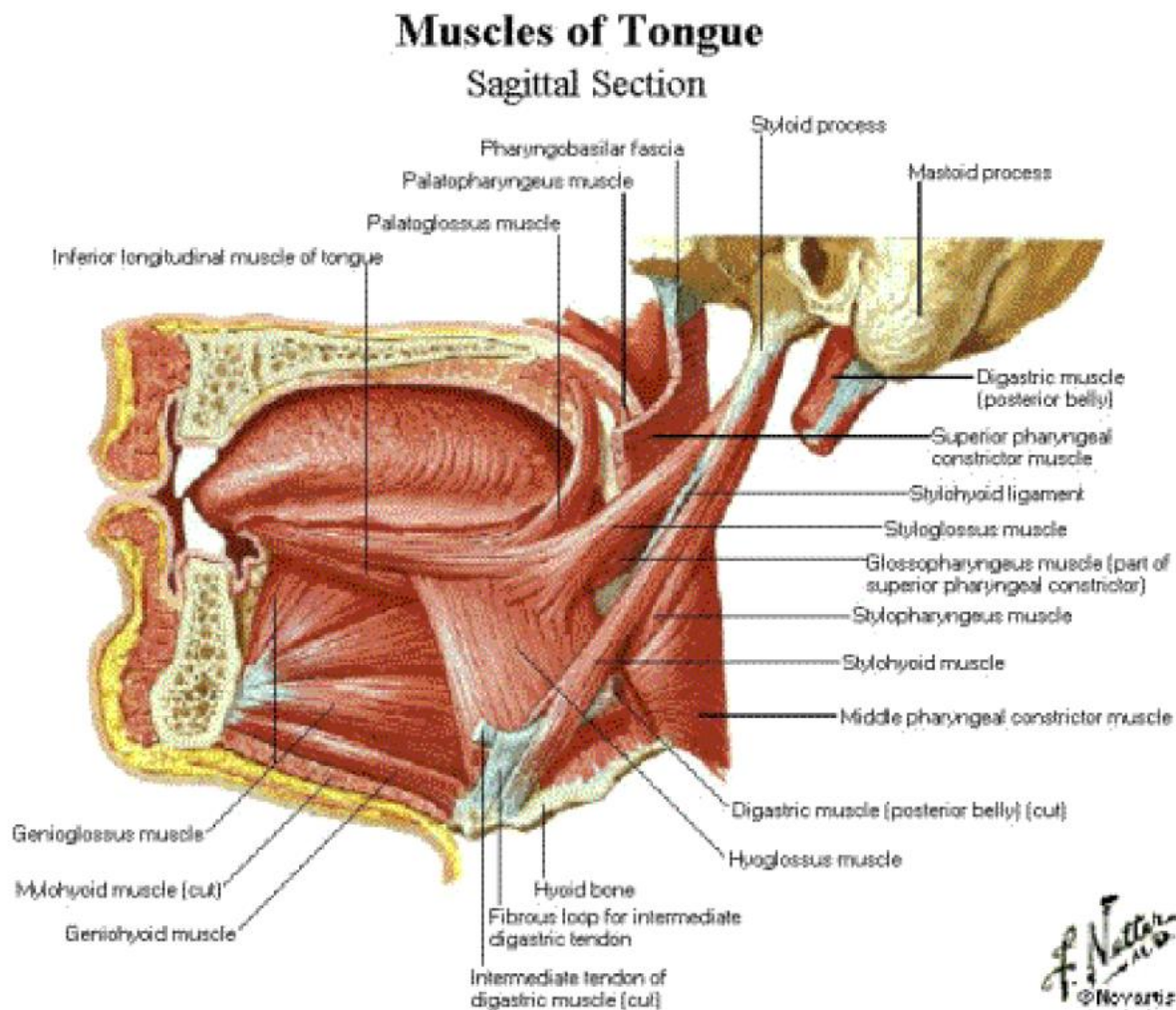
F. Netter M.D.
© Novartis

Anatomical basis

Vue de profil

Netter (1984)
Atlas of Human Anatomy.

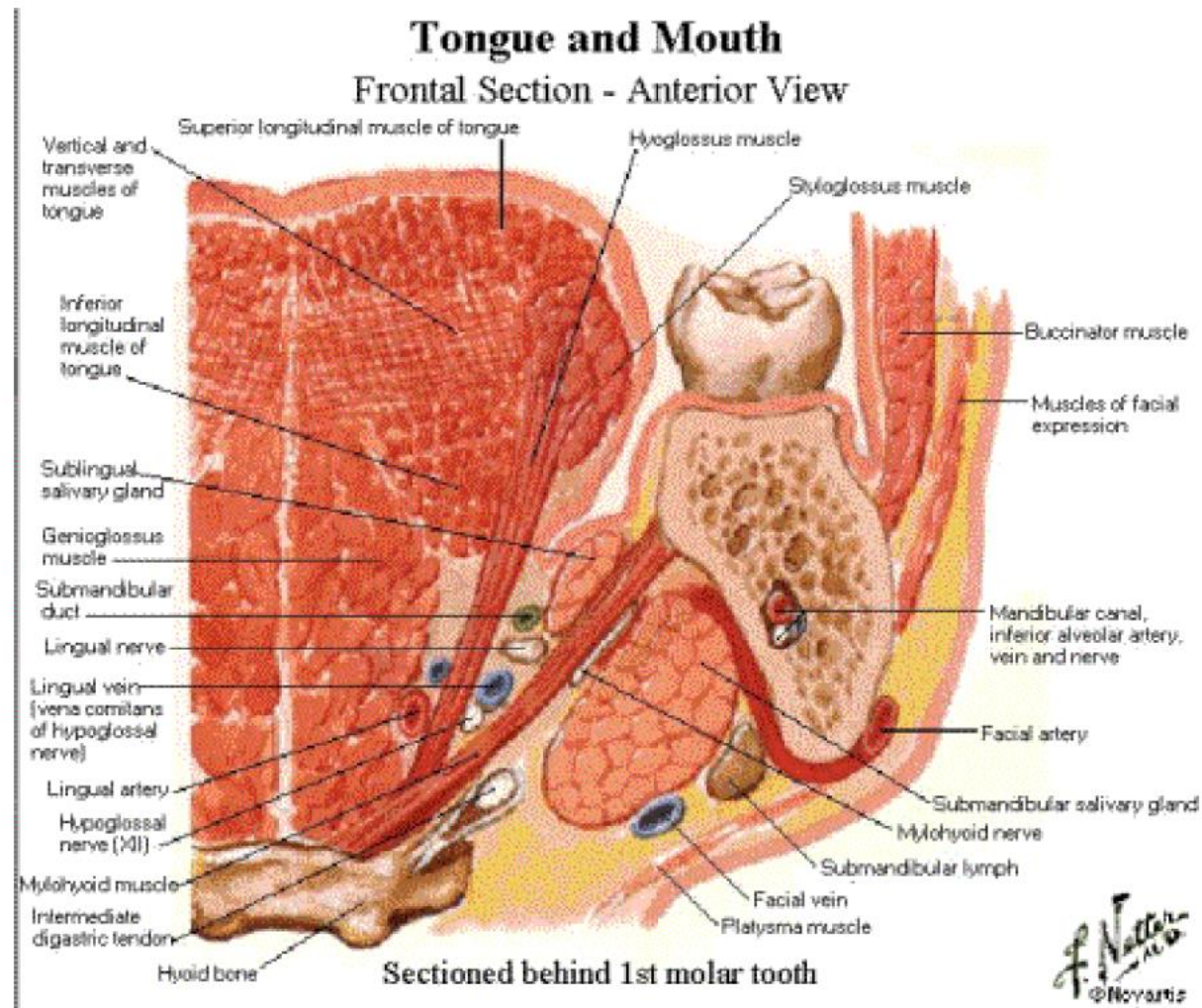
Muscular hydrostat



Anatomical basis

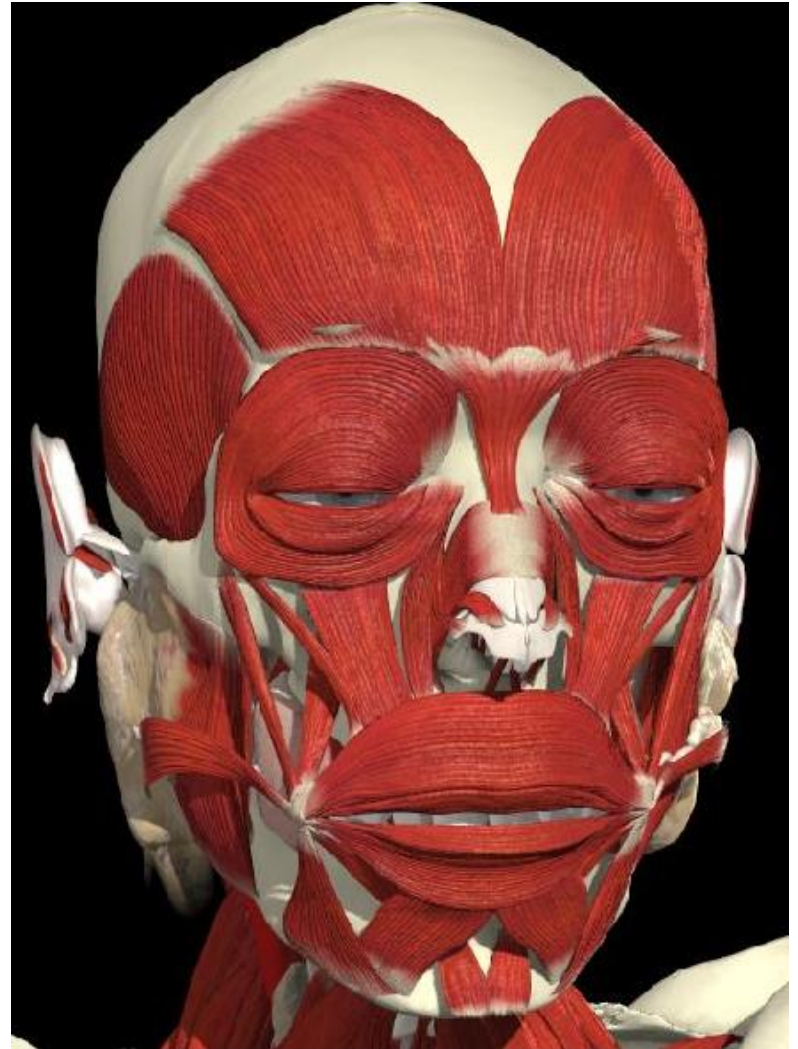
Coupe transversale

Netter (1984)
Atlas of Human Anatomy.



Anatomical basis

Berkovitz et al. (2003), 3D Head and Neck Anatomy with Special Senses and Basic Neuroanatomy (www.anatomy.tv)



Anatomical basis



O'Dwyer NJ et al. JSHR, 1981

Mesures cinématiques

Electromagnétométrie

ElectroMagnetic Midsagittal Articulometer (EMMA)

Perkell J.S et al.(1992). The Journal of the Acoustical Society of America, 92(6), 3078-3096.

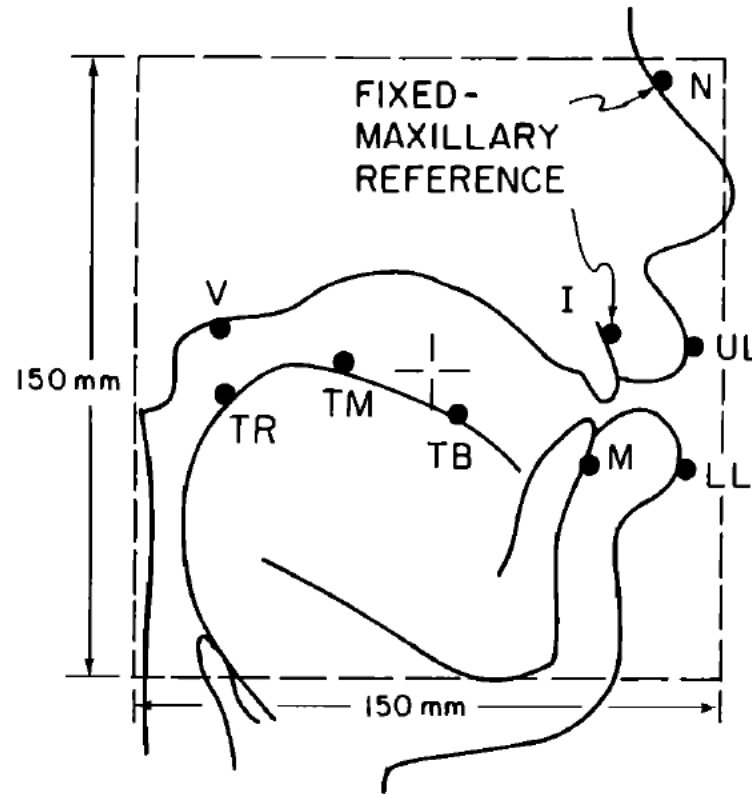
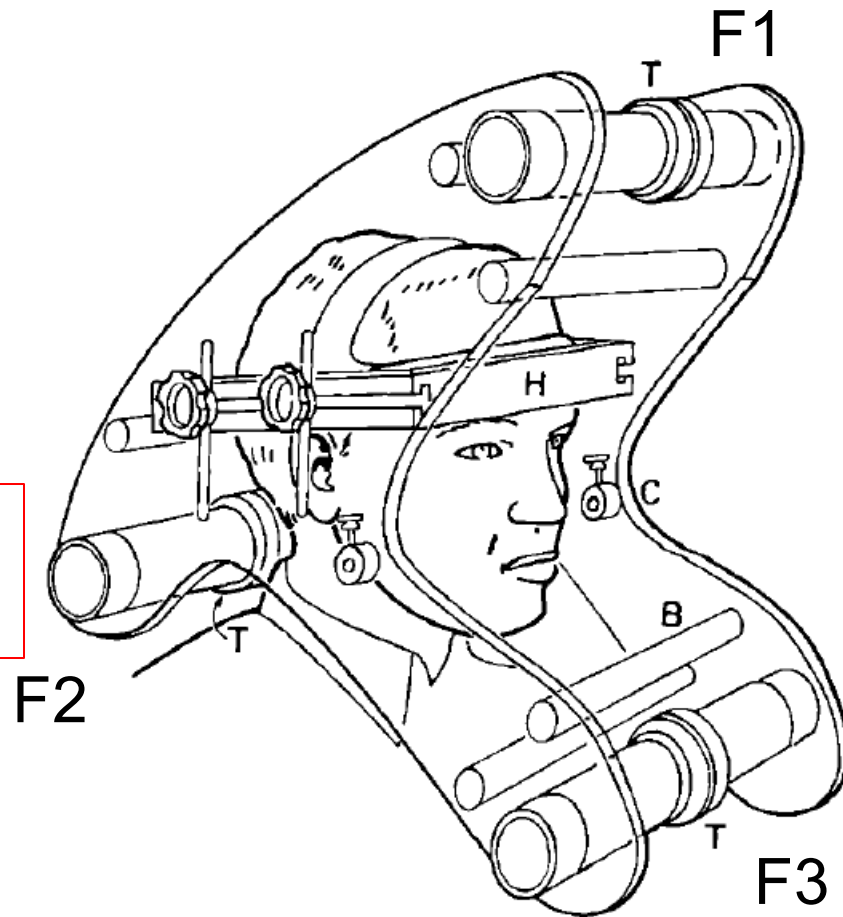


FIG. 1. A schematic midsagittal view of a subject with nine possible measurement points (indicated by filled circles) corresponding to fixed points on the bridge of the nose (N) and the upper central incisors (I) for a maxillary frame of reference, and movable points on the mandible (M), lips (UL,LL), tongue (TB, TM, TR) and velum (V).

Perkell J.S et al.(1992). The Journal of the Acoustical Society of America, 92(6), 3078-3096.

F1, F2, F3
autour de 60 kHz



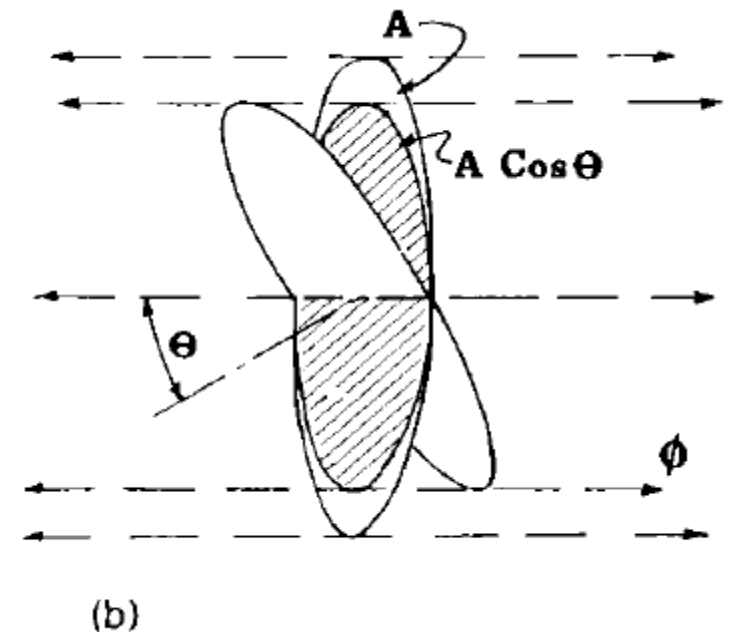
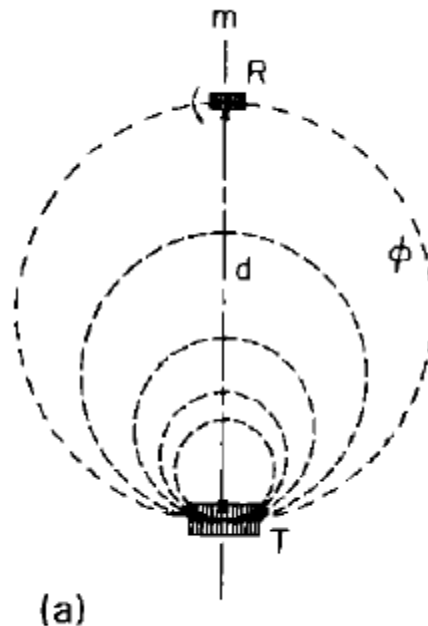
ElectroMagnetic Midsagittal Articulometer (EMMA)

Perkell J.S et al.(1992). The Journal of the Acoustical Society of America, 92(6), 3078-3096.

$$i(t) = \frac{k \cdot \phi(t)}{d^3}$$

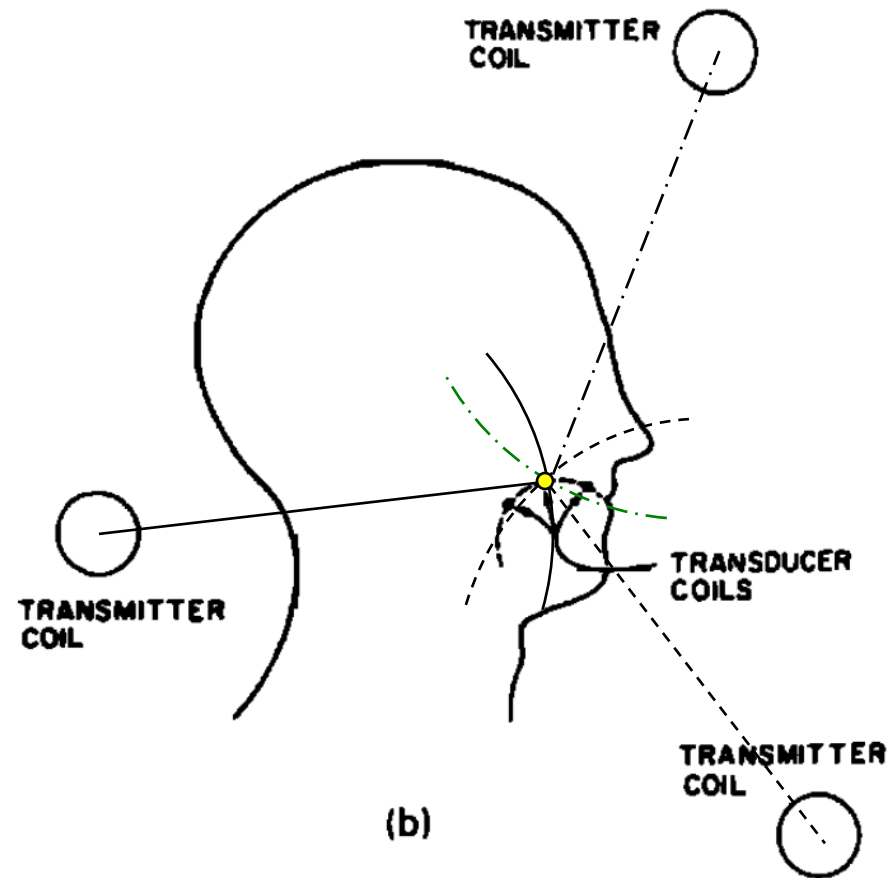
$$i(t) = \frac{k \cdot \phi(t)}{d^3} * \cos \theta$$

R: Transducer coil
T: Transmitter coil



ElectroMagnetic Midsagittal Articulometer (EMMA)

Perkell J.S et al.(1992). The Journal of the Acoustical Society of America, 92(6), 3078-3096.



Electromagnétomètres

2D

AG200 – Carstens



5D

AG500 – Carstens



5D

AG501 – Carstens



5D

Wave – NDI



Electromagnétométrie: 5D Articulographes

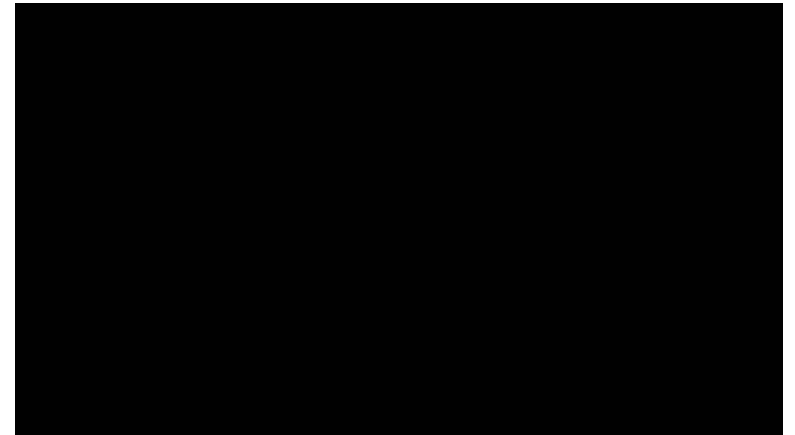
Les capteurs ne doivent plus être dans le plan sagittal !

5 variables:

- 3 coordonnées cartésiennes : x , y , z
- 2 angles : inclinaison (tilt)
rotation horizontale (twist)

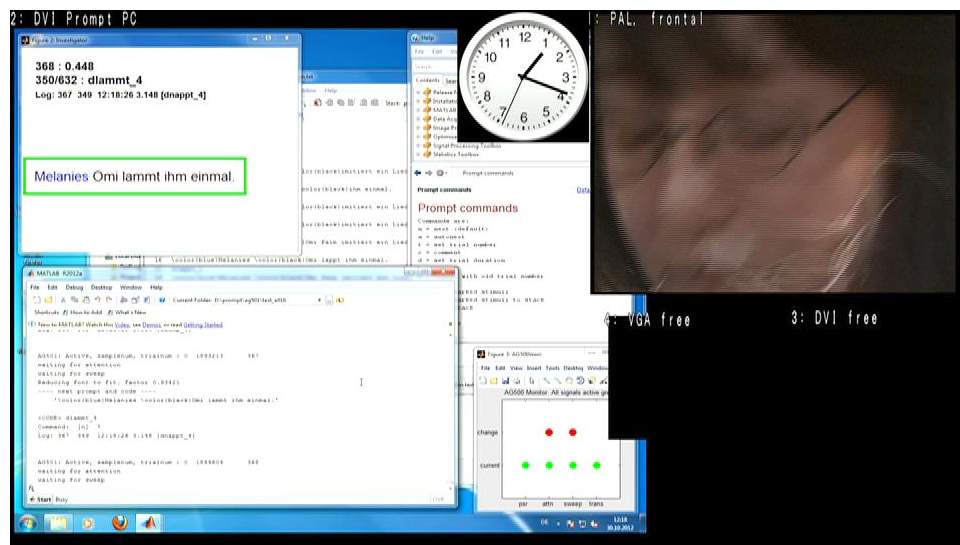
6 bobines émettrices

→ Pas de solution analytique – Problème optimal



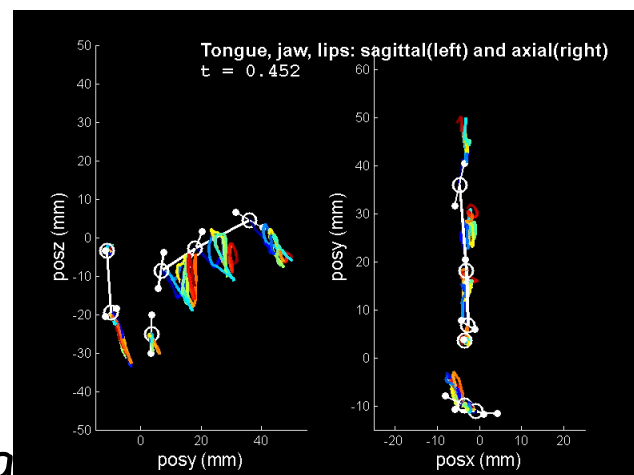
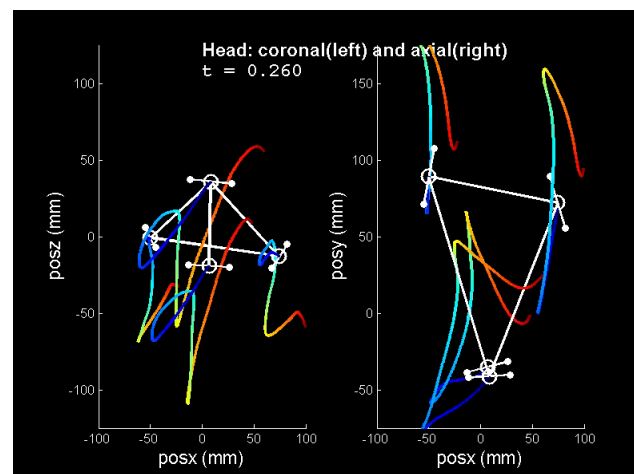
Electromagnétométrie: 5D Articulographes

Correction efficace des mouvements de la tête



Phil Hoole

Institut für Phonetik und Sprachverarbeitung
Munich



Limits

- Number of recorded points
- Relatively expensive

Perkell J.S et al.(1992). The Journal of the Acoustical Society of America, 92(6), 3078-3096.

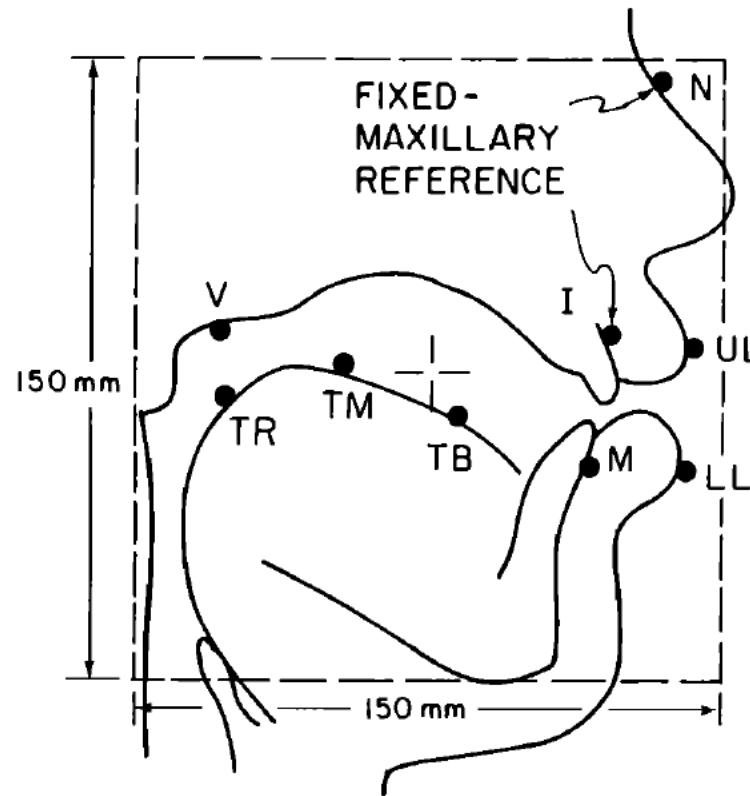
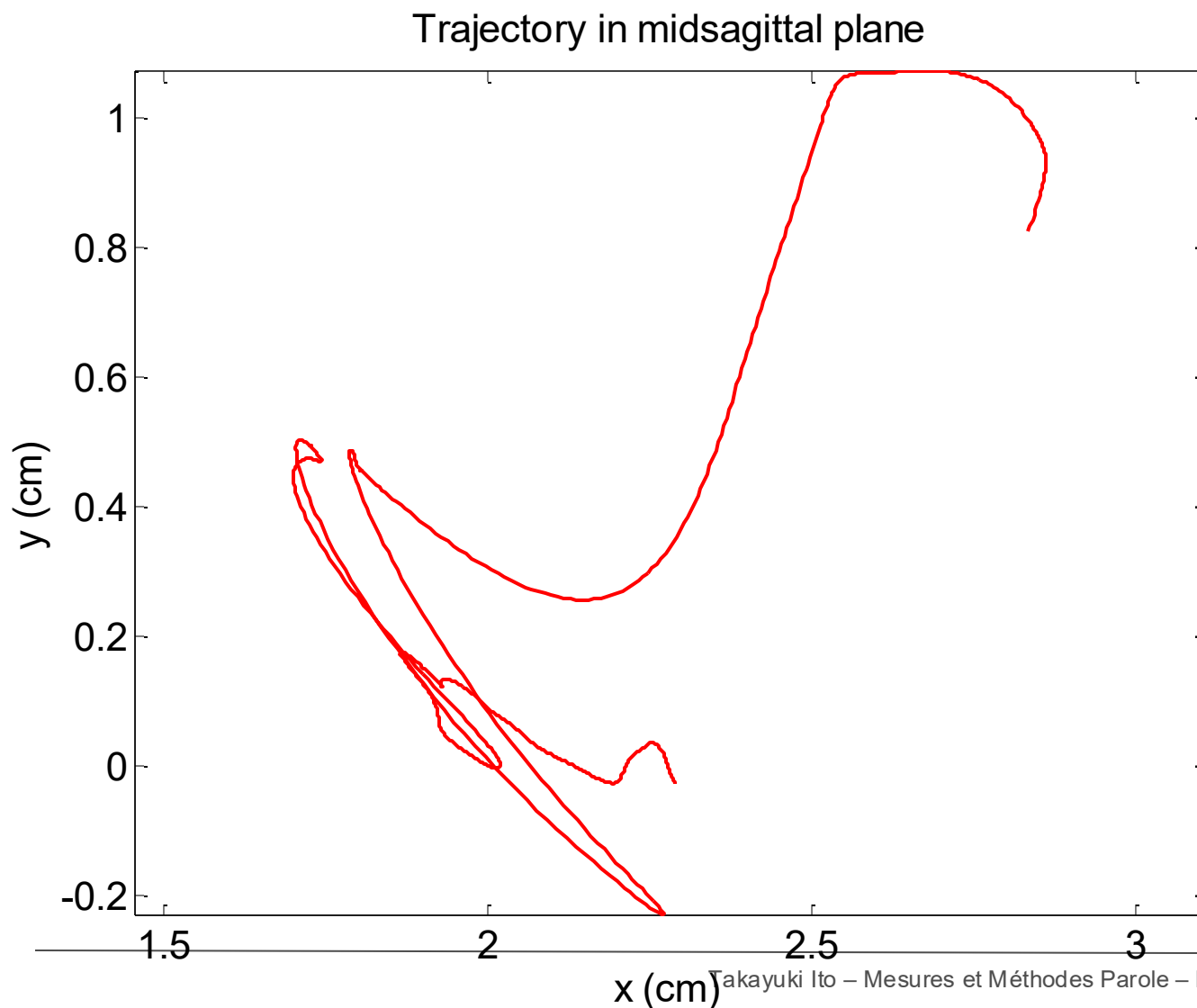
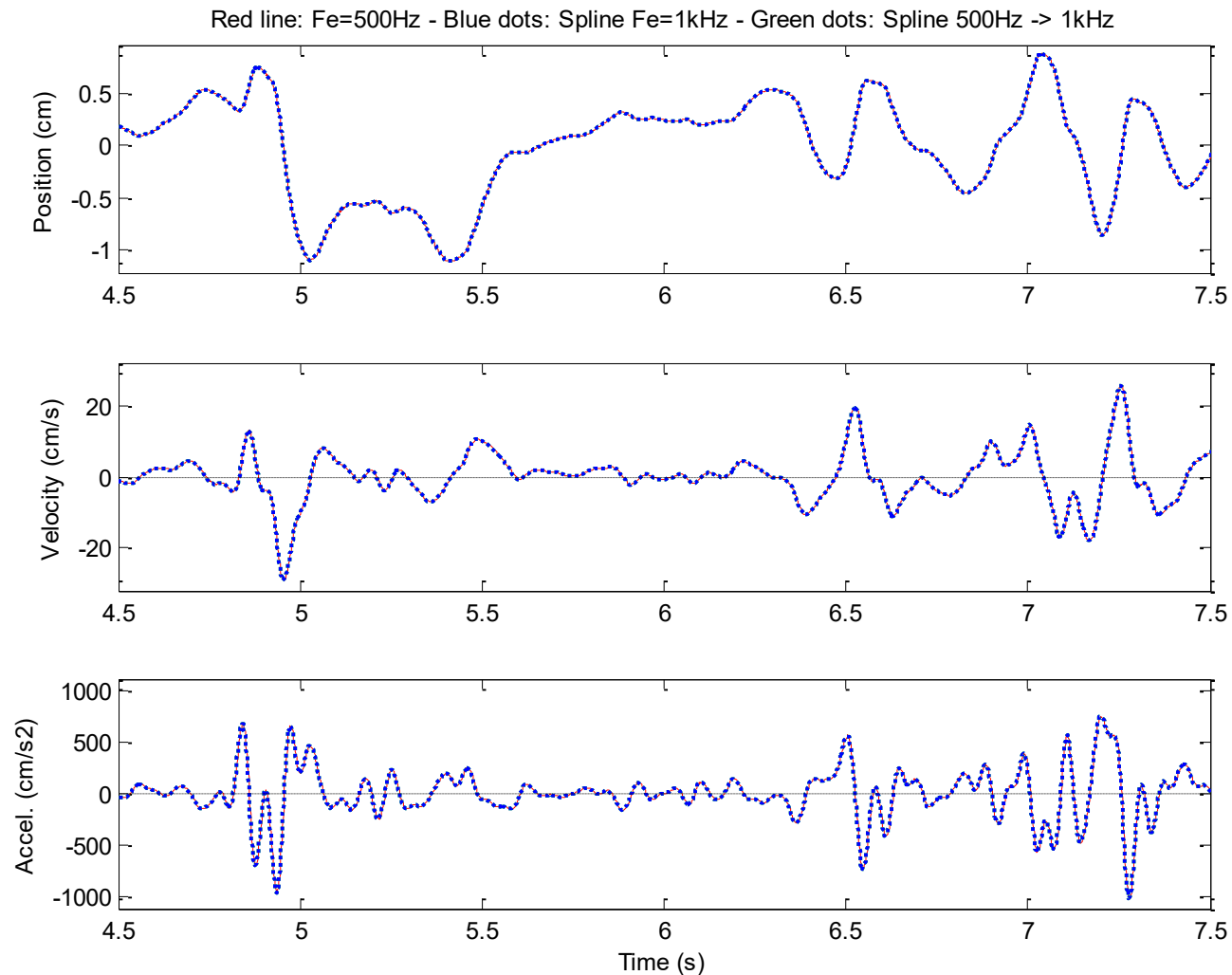


FIG. 1. A schematic midsagittal view of a subject with nine possible measurement points (indicated by filled circles) corresponding to fixed points on the bridge of the nose (N) and the upper central incisors (I) for a maxillary frame of reference, and movable points on the mandible (M), lips (UL,LL), tongue (TB, TM, TR) and velum (V).

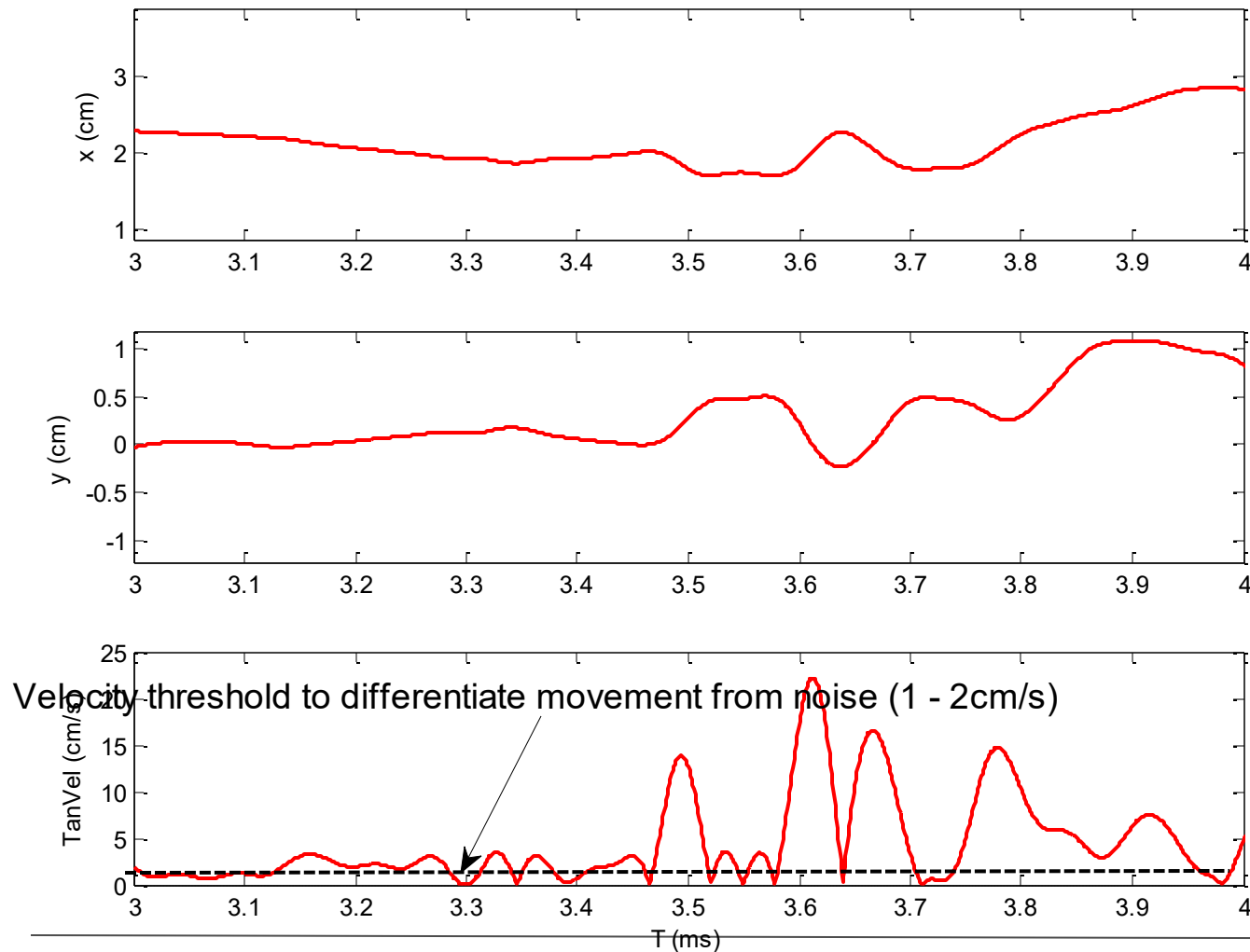
Electromagnétomètres : Mesures



Electromagnétomètres : Mesures

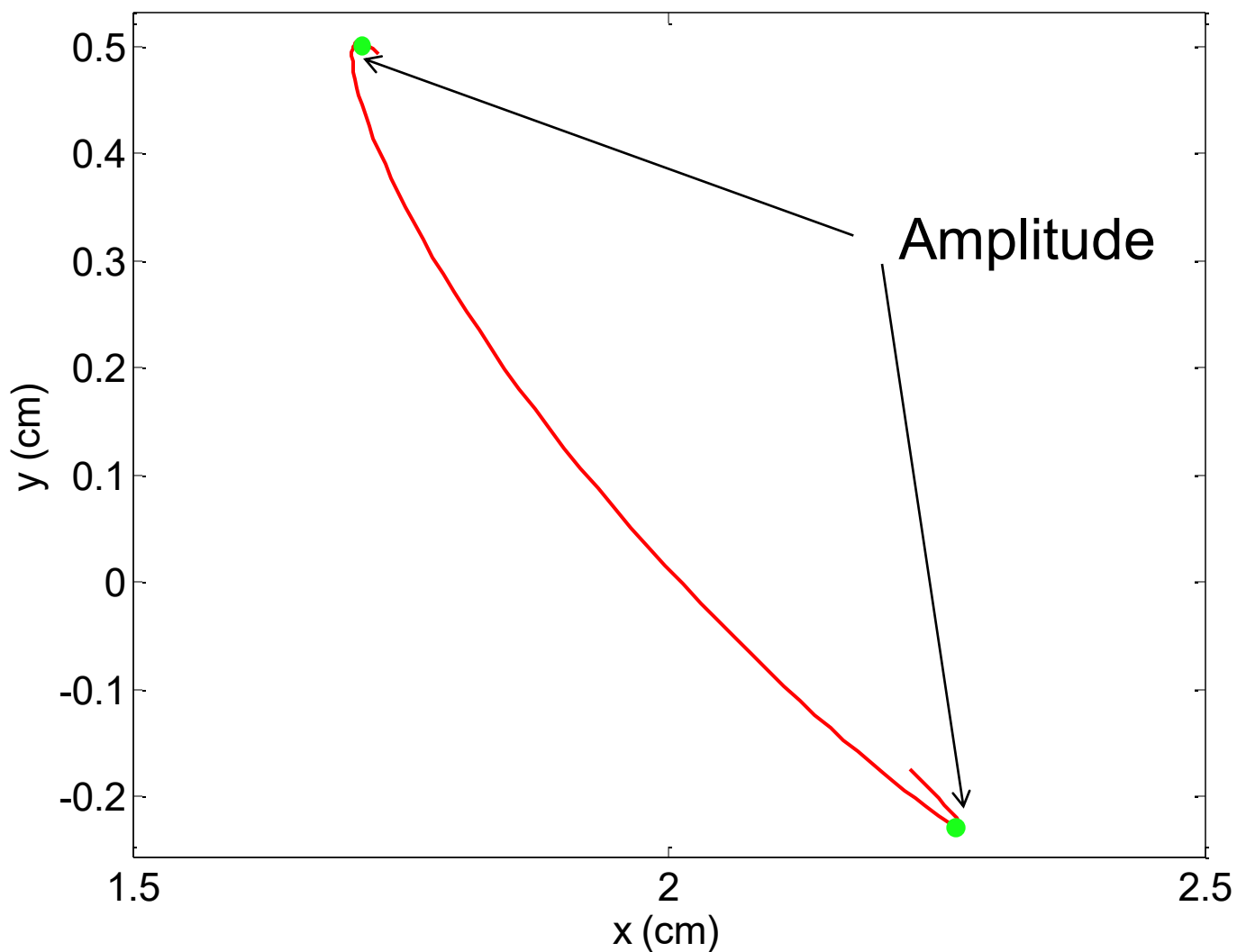


Electromagnétomètres : Segmentation



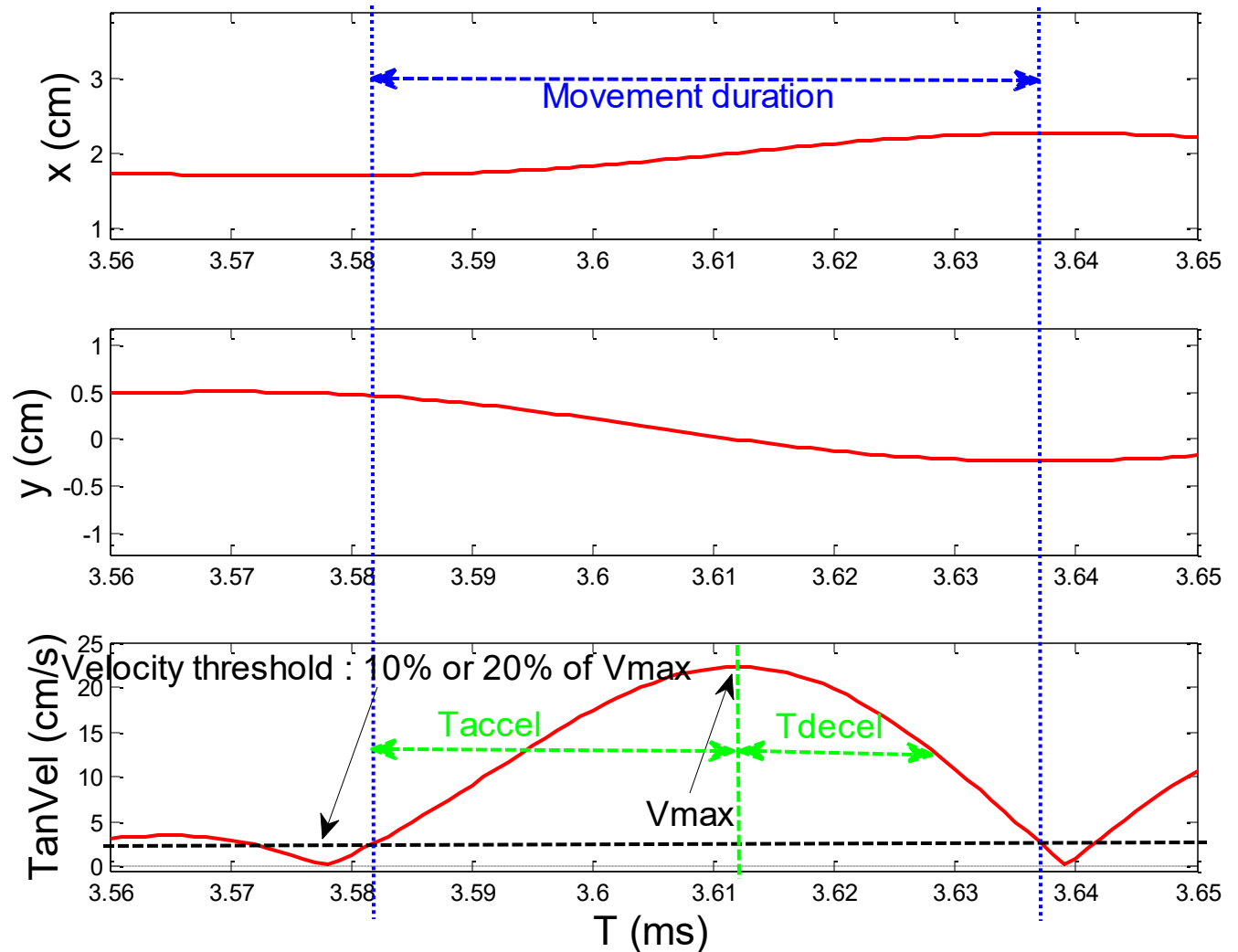
Articulographie : Mesures cinématiques

Trajectory in midsagittal plane



Electromagnétomètres : Mesures

Profil de vitesse



Electromagnétomètres : Evaluer l'optimisation des gestes

Nelson, 1983

time cost: $T = \text{movement time}$

force cost: $A = \max_{t \in (0, T)} |u(t)|,$

impulse cost: $I = \frac{1}{2} \int_0^T |u(t)| dt,$

energy cost: $E = \frac{1}{2U} \int_0^T u^2(t) dt,$

jerk cost: $J = \frac{1}{2} \int_0^T \dot{a}^2(t) dt,$

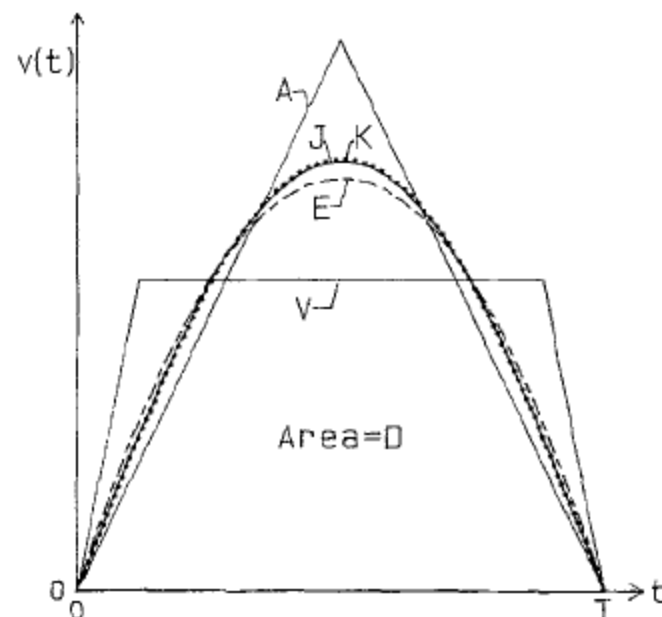
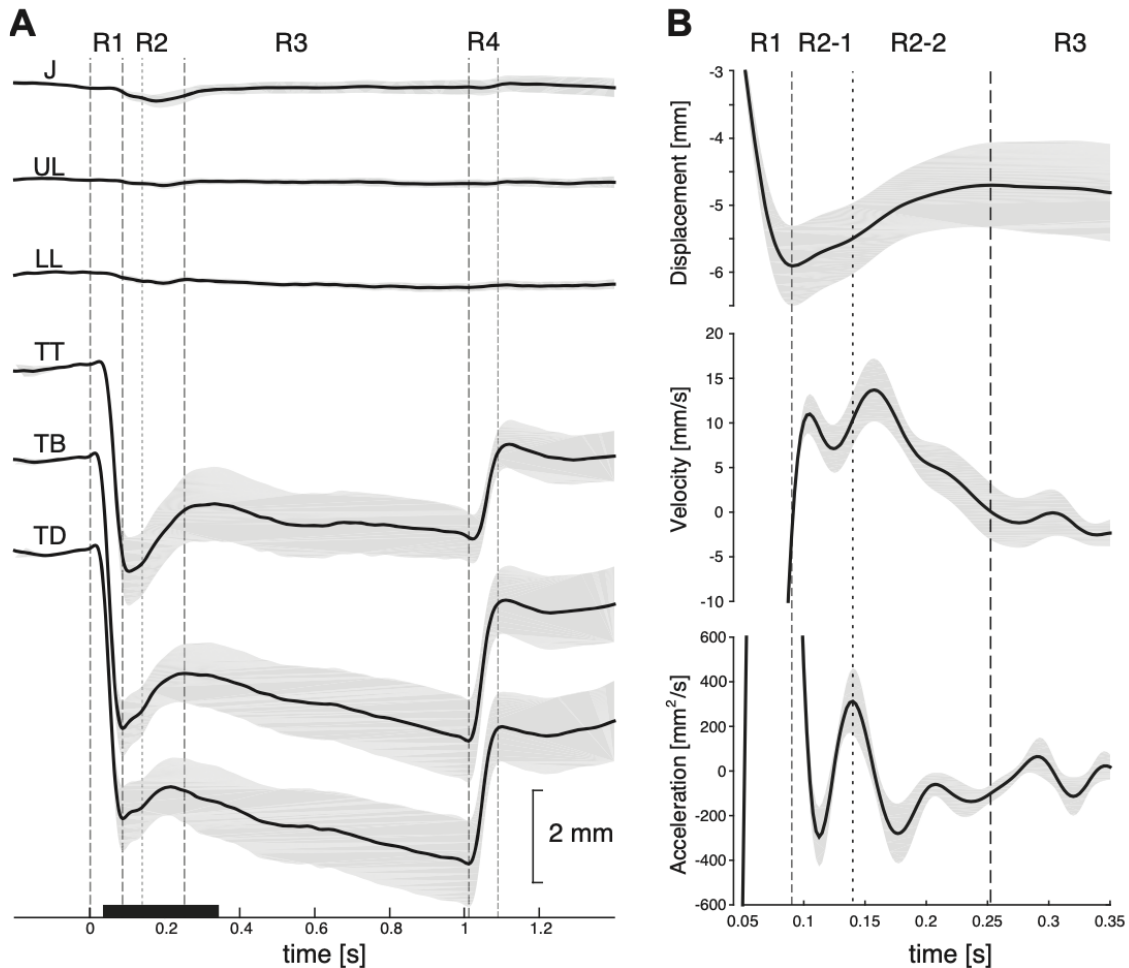


Fig. 3. Comparison of velocity patterns for the same movement time and distance which are optimum with respect to five different objectives: A -minimum peak acceleration (solid line), E -minimum energy (dashed line), J -minimum jerk (solid), K -constant stiffness (dotted), and V -minimum peak velocity, or impulse (solid line)

Electromagnétomètres : Extract movement characteristics

Ito et al., 2020



Mesures cinématiques

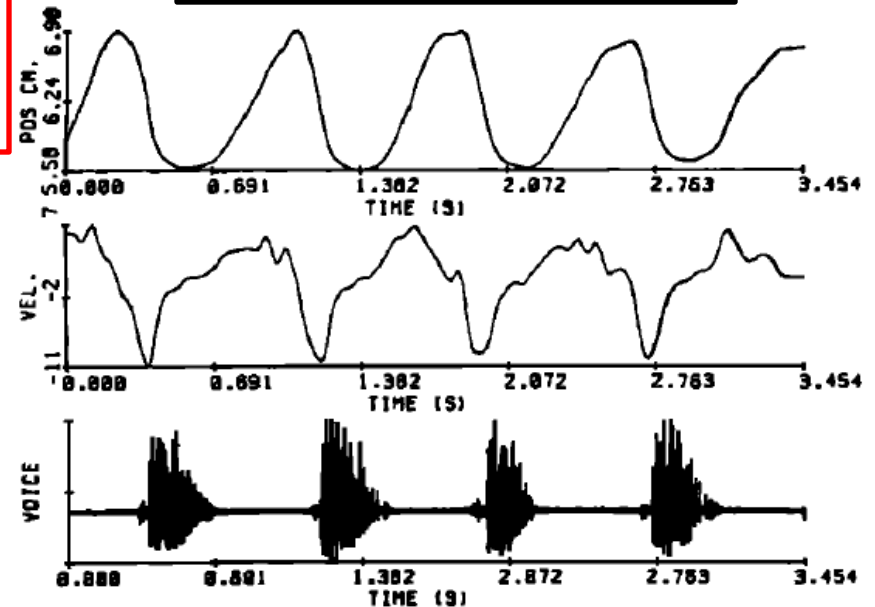
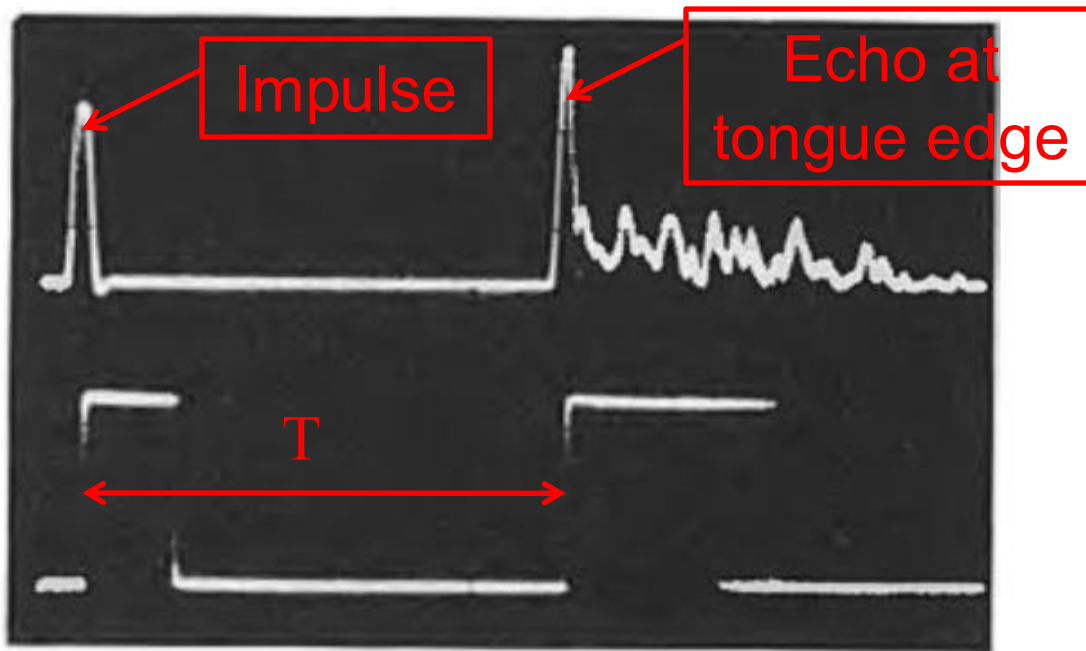
Echographie – ultrasound system

Echographie - Principes

- Premiers travaux en parole
 - Keller & Ostry (JASA, 1983)
 - Ostry & Munhall (JASA, 1985)

$$D = 1/2(T * V_{\text{sound}})$$

$$V_{\text{sound}} = 1540 \text{ m/s}$$

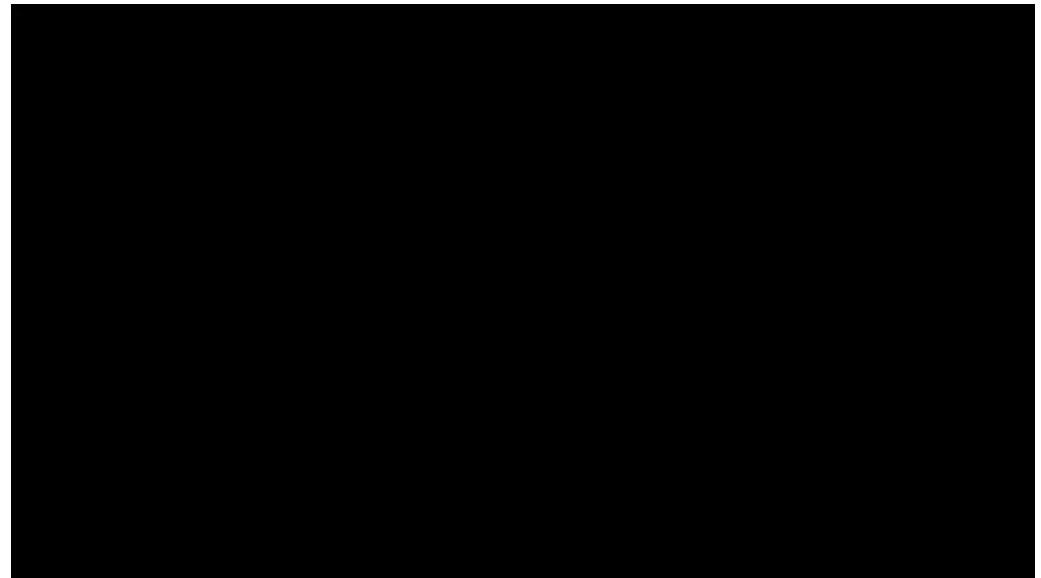


Tongue dorsum – $F_s = 1 \text{ kHz}$

Picker 104 – 3.5 MHz – Single transducer
39

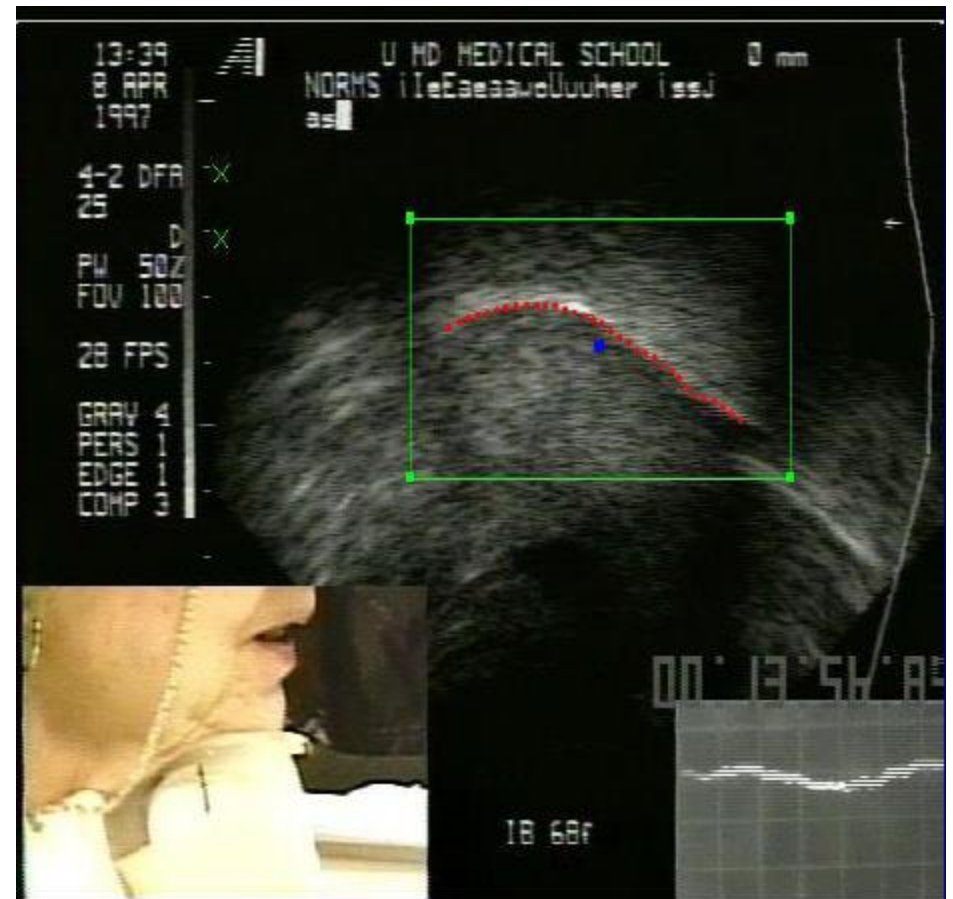
Echographie

Unser, M., & Stone, M. (1992).
*The Journal of The
Acoustical Society of
America*, 91(5), 3001-3007.



Echographie

- Acoustic Imaging, Model AI5200S
- 2-4 MHz multifrequency array transducer
- $F_s = 28$ Hz
- 90 degree sector
- Contour detection
- Edgetrack - © Video/Image Modeling and Synthesis Lab

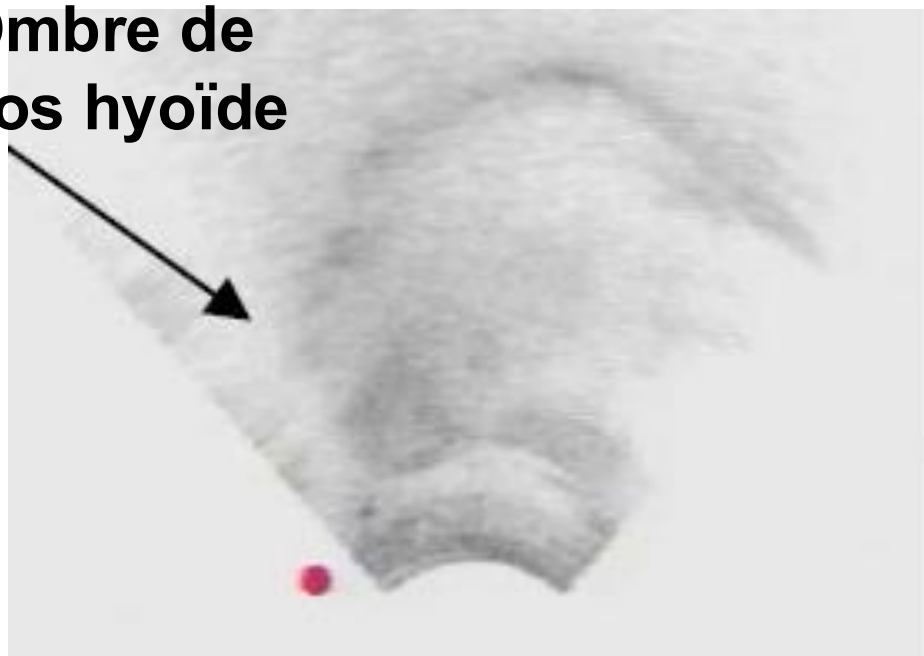


Stone et al., 2010 – Ultrafest V

<http://www.haskins.yale.edu/conferences/UltrafestV/present.html>

Echographie : Limites

Ombre de l'os hyoïde

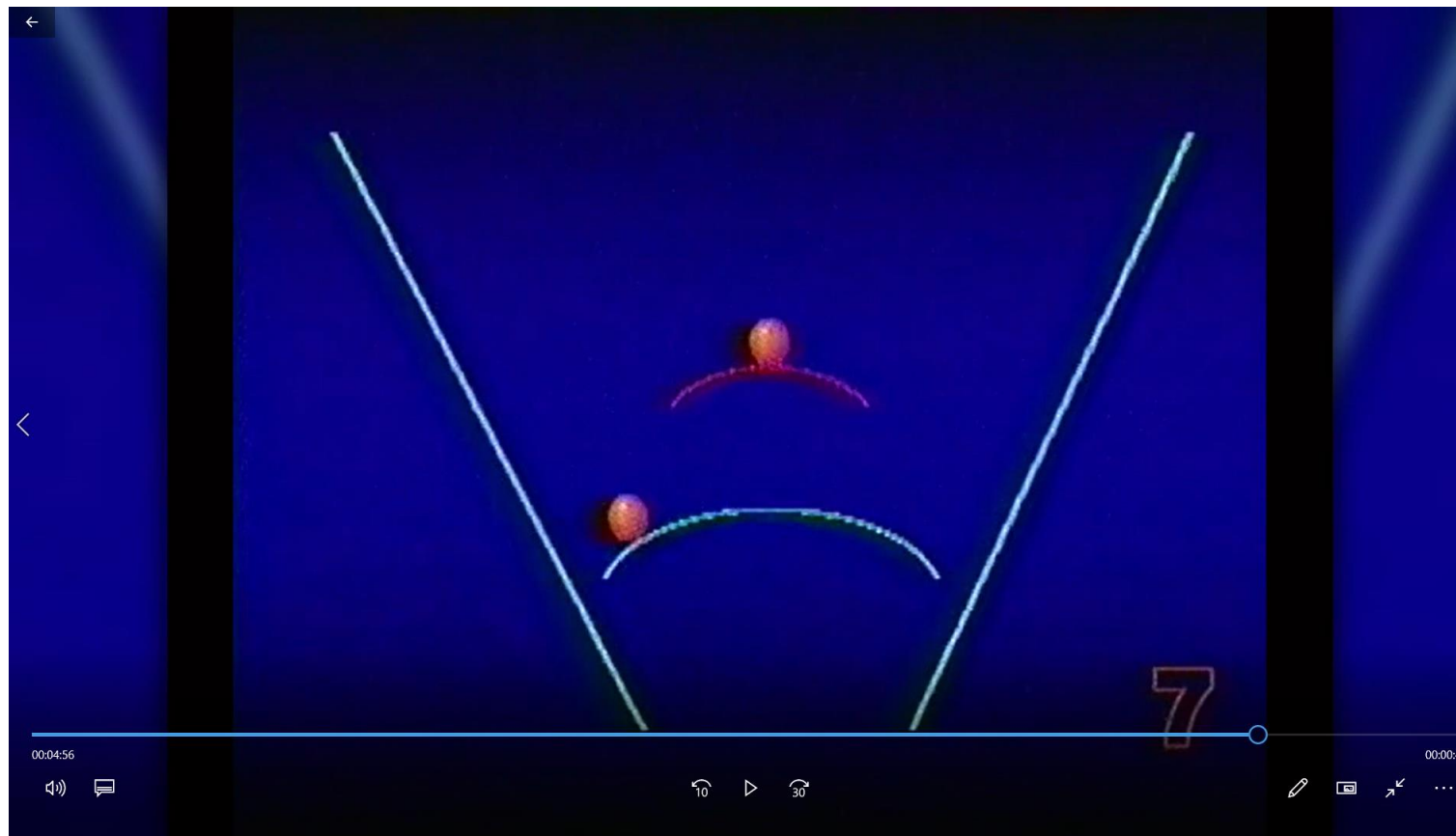


Ombre de la mandibule



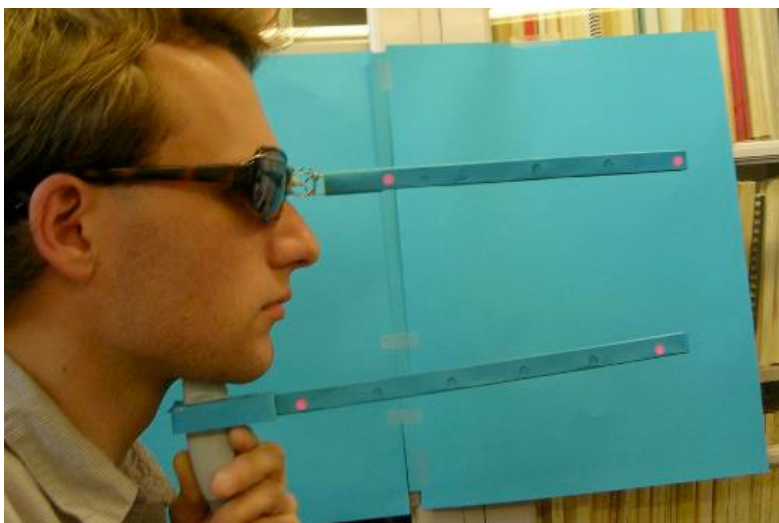
Aubin, 2006

Echographie : Limites



Pas de point de chair

Echographie – Limiter les mouvements de la tête



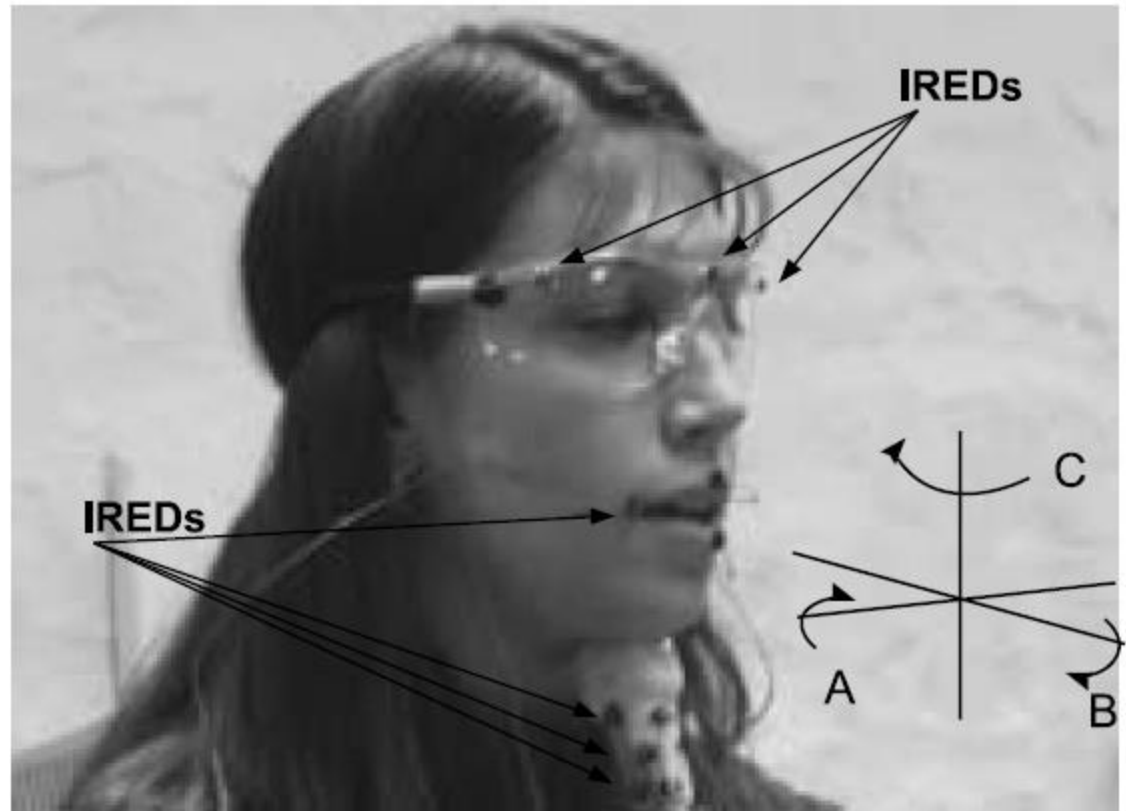
Mielke et al., 2005, University of Arizona



HATS
Stone & Davis, JASA 1995
Image from Hueber, PhD Thesis 2006

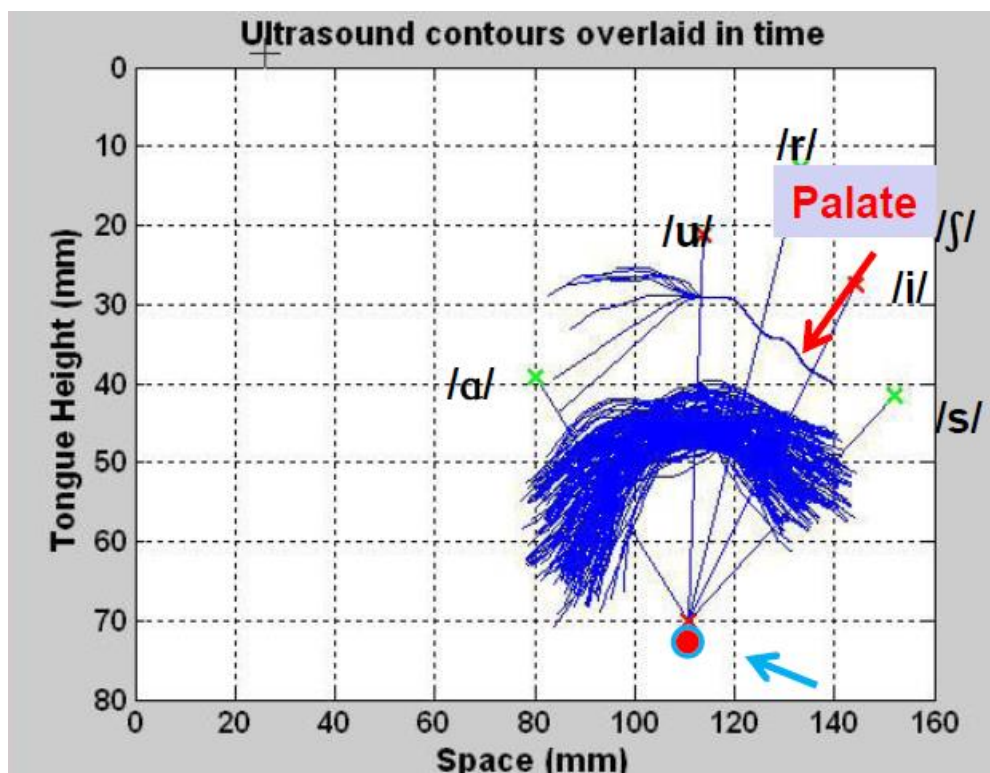
Echographie – Compenser les mouvements de la tête

Hocus (Haskins Lab)
Whalen et al., JSLHR
2005



Echographie

Stone et al., 2010, Ultrafest.



CAVITE (Contour Analysis and Visualization Technique)

Echographie : « Speckle tracking »

Jacob et al., ISSP08

Calcule les variations entre deux images successives



Speckle

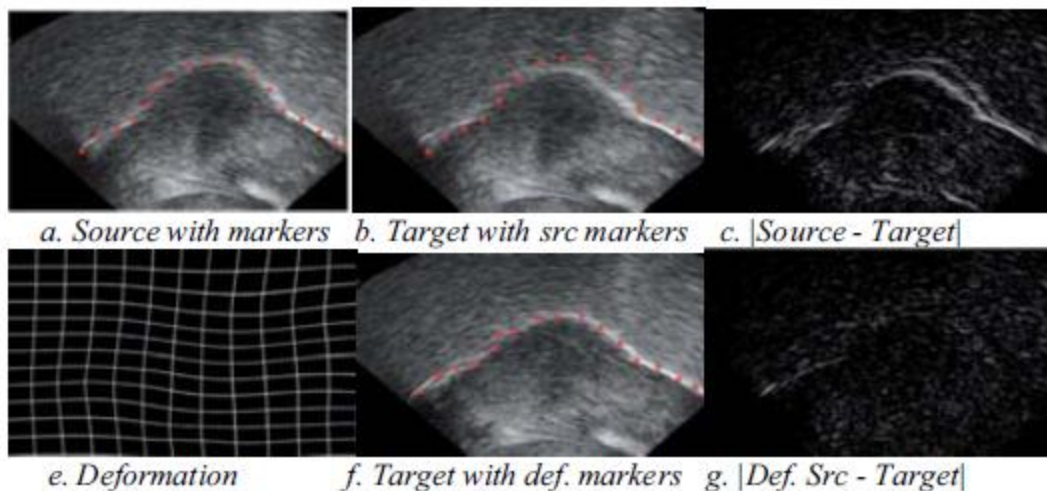


Figure 1: Illustration of the registration algorithm. (a) is the source image with virtual tongue markers (b) is the target image (next frame) with the markers at the same location as the source. (c) is the absolute difference between the source and the target images. (e) is the estimated deformation and (f) is the target image with the deformed markers. (g) is the difference between the deformed source and the target images.

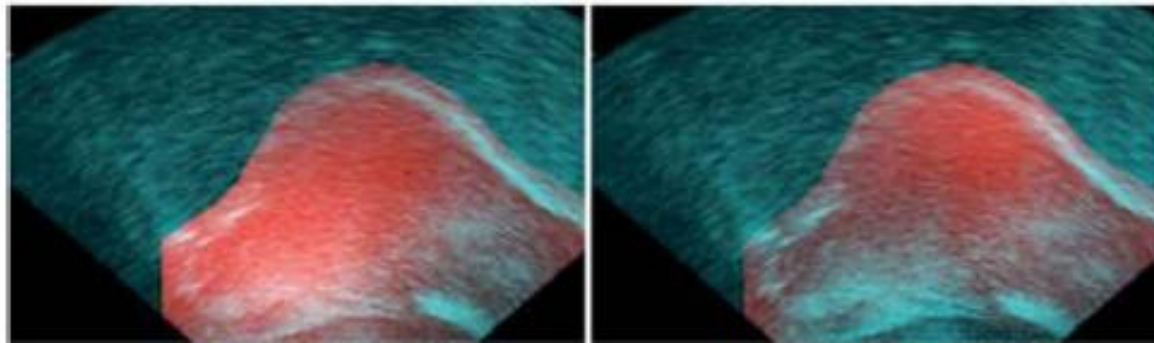
Articulographie : Speckle tracking

Jacob et al., ISSP08

Variation des formes de la langue dans une séquence CV

Déplacements de la Consonne (Ref) à la Voyelle

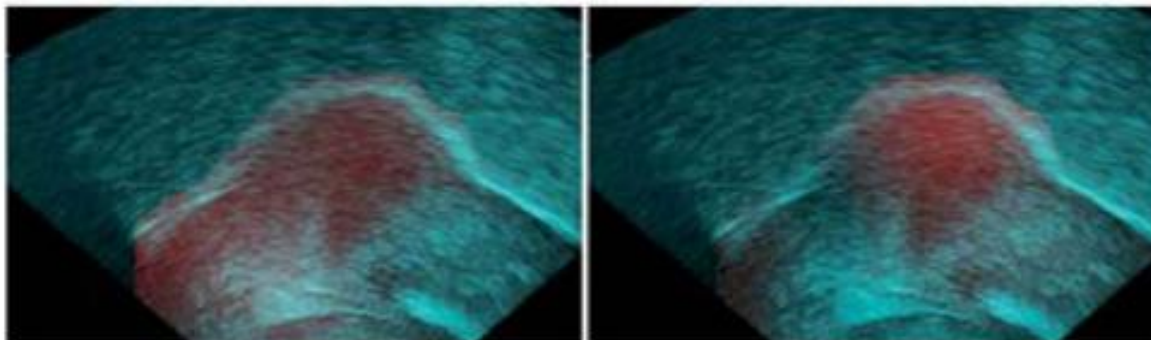
Début de
groupe
accentuel



horizontal

vertical

Début de
mot



horizontal

vertical

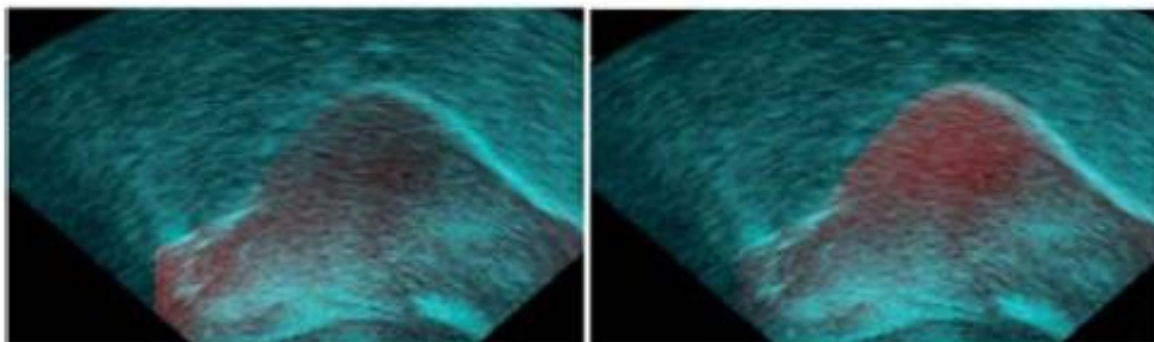
Articulographie : Speckle tracking

Jacob et al., ISSP08

Variation des formes de la langue dans une séquence CV

Vitesse

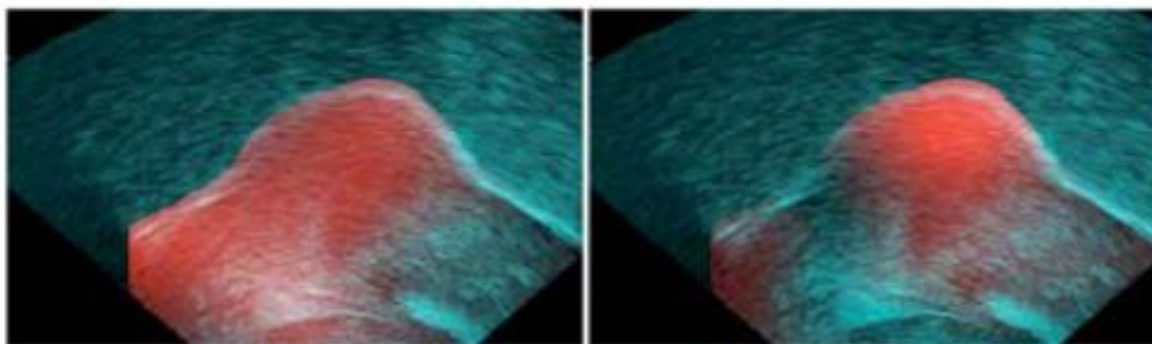
Début de
groupe
accentuel



horizontal

vertical

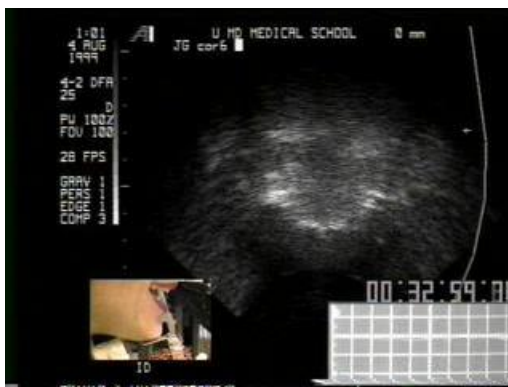
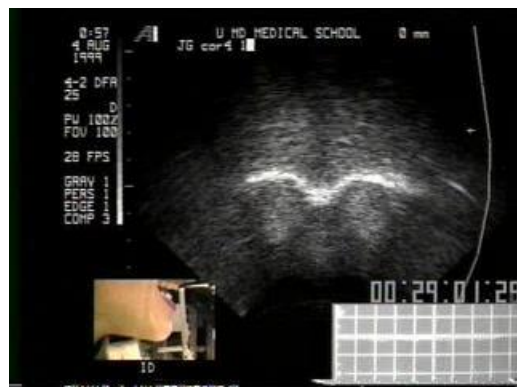
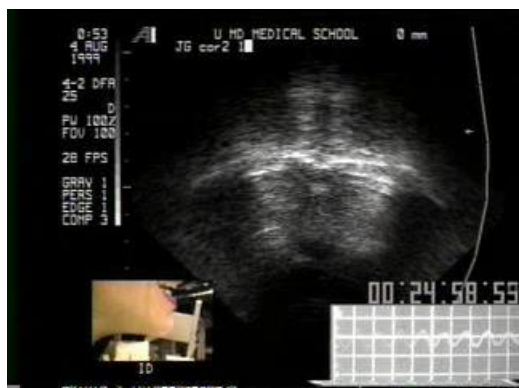
Début de
mot



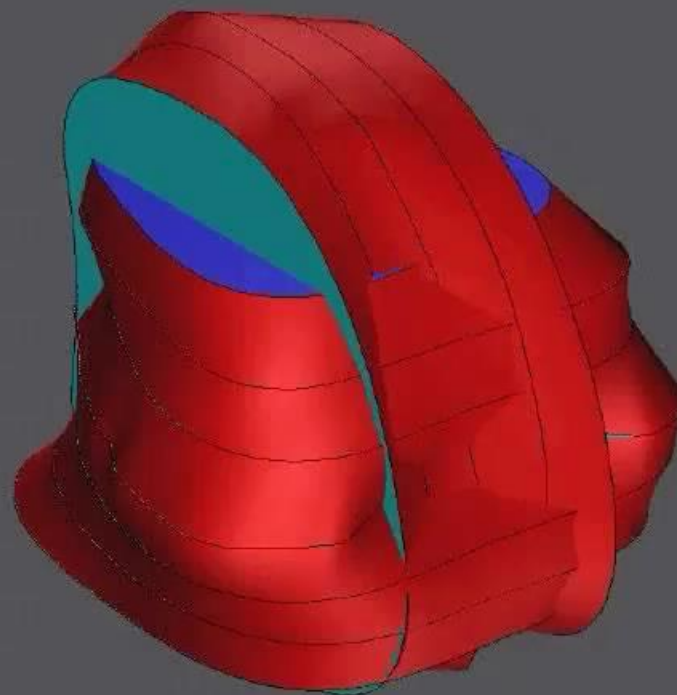
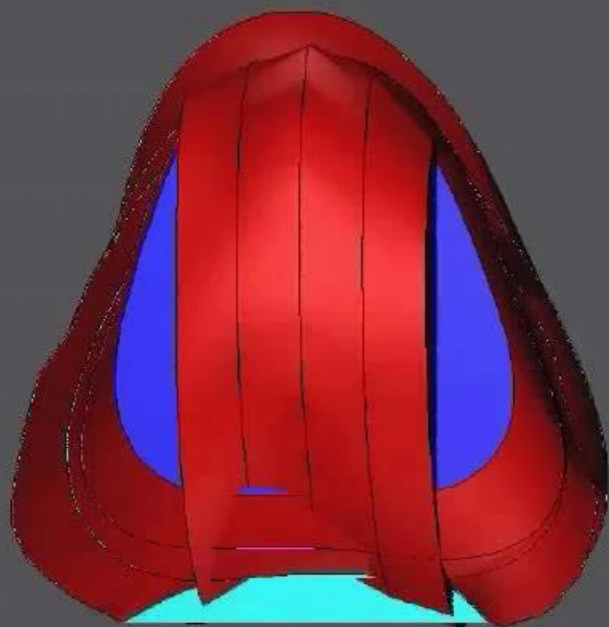
horizontal

vertical

Echographie : Formes 3D de la langue



Echographie : Formes 3D de la langue



Syllabe 'scha' en anglais

Mesures cinématiques sur les cordes vocales

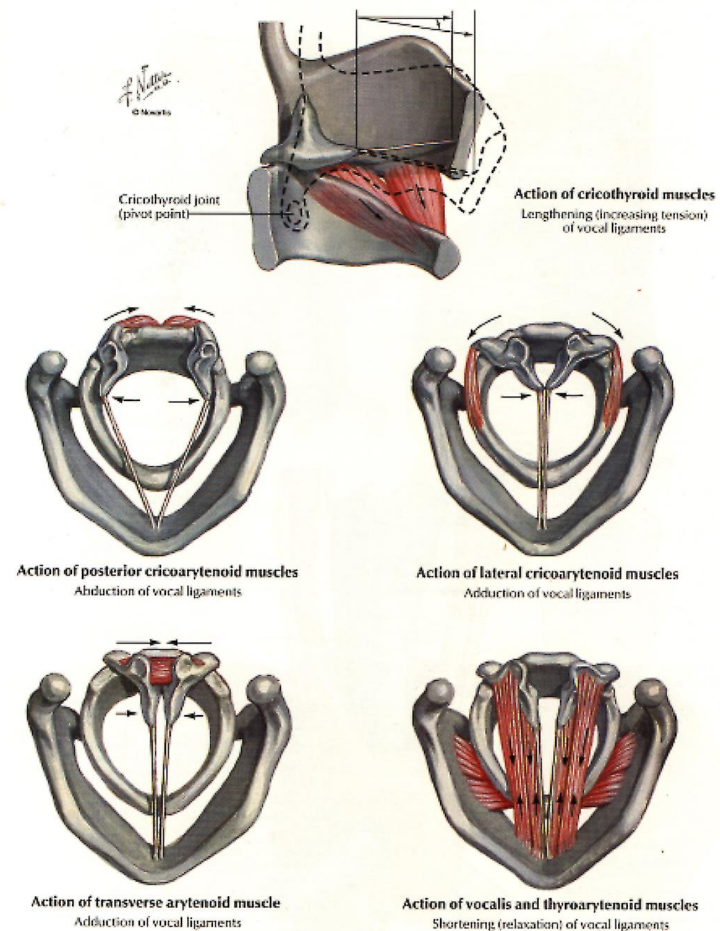
Endoscopie & Electroglossographie

Endoscopie : Le larynx

Laryngeal endoscopy

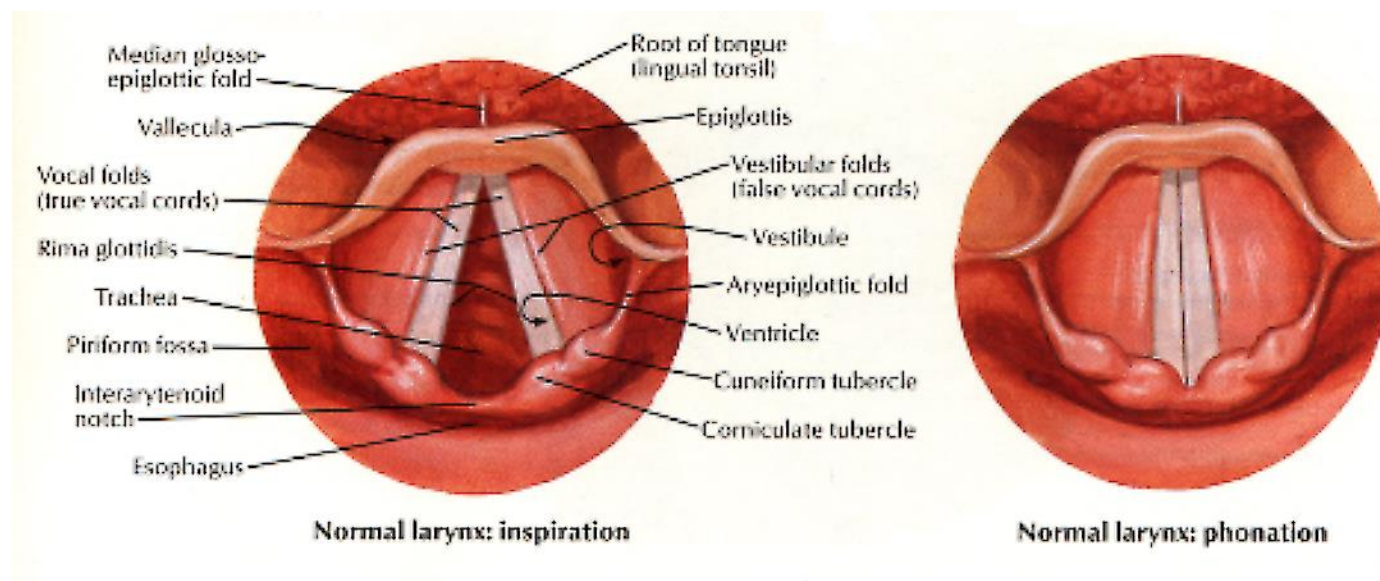
Cartilages et muscles

Netter (1984) Atlas of Human Anatomy.



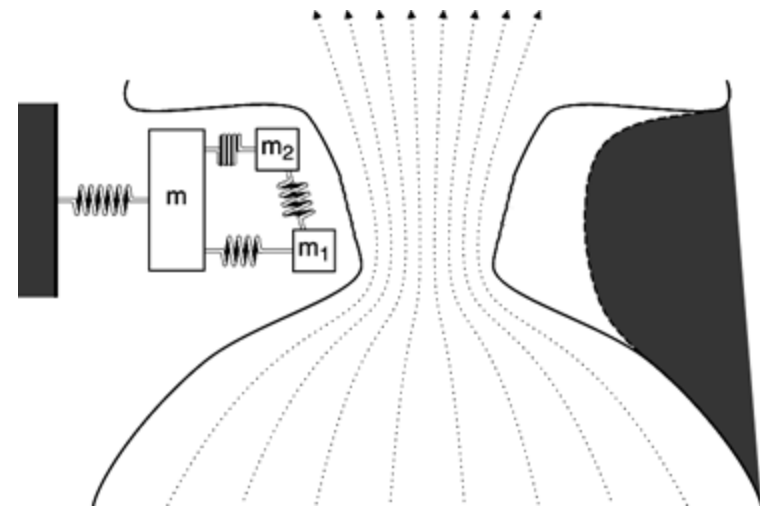
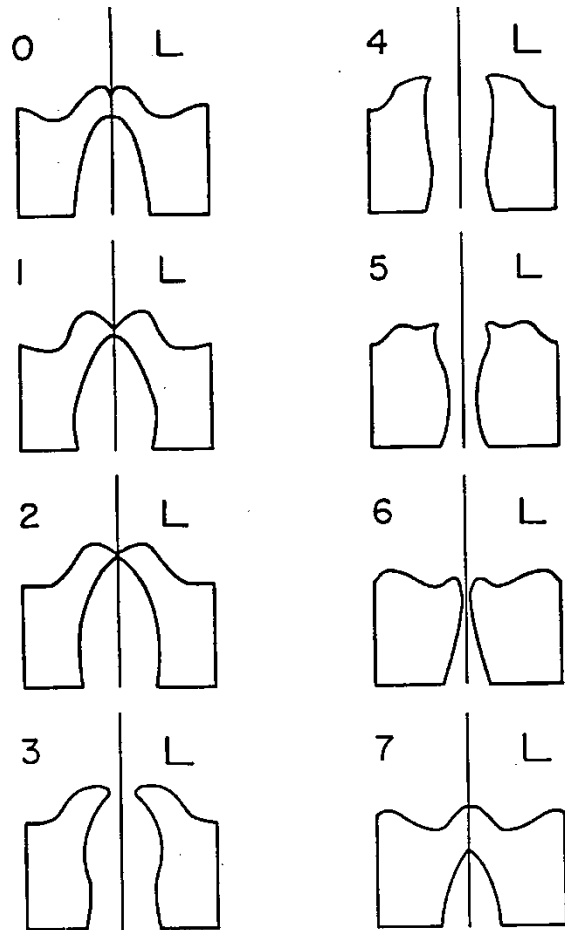
Endoscopie : les cordes vocales

Les plis vocaux



Netter (1984) Atlas of Human Anatomy.

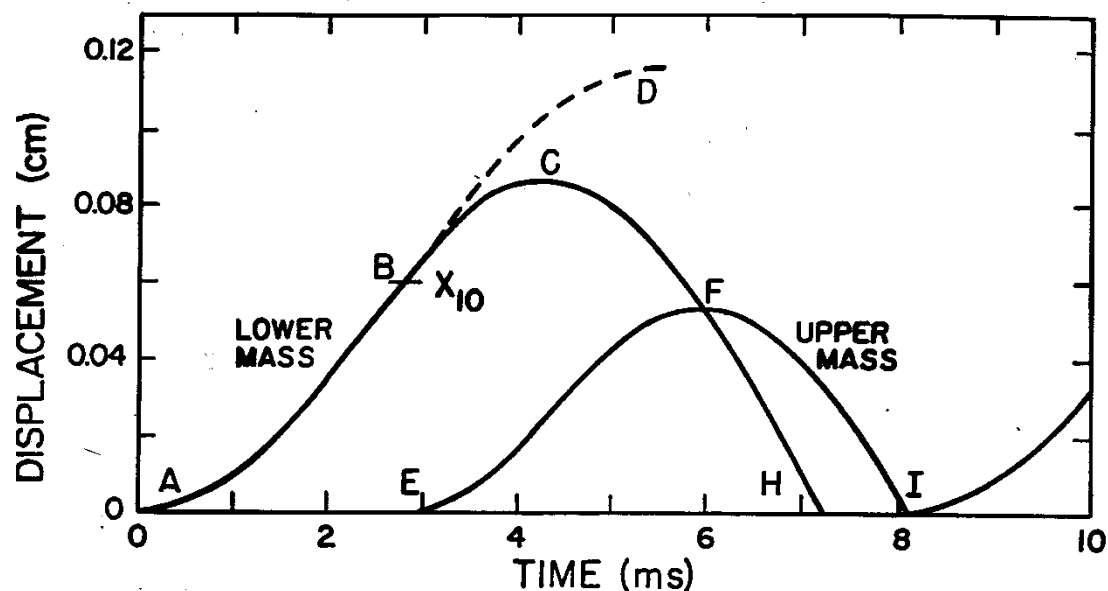
Vibration des cordes vocales: Voisement



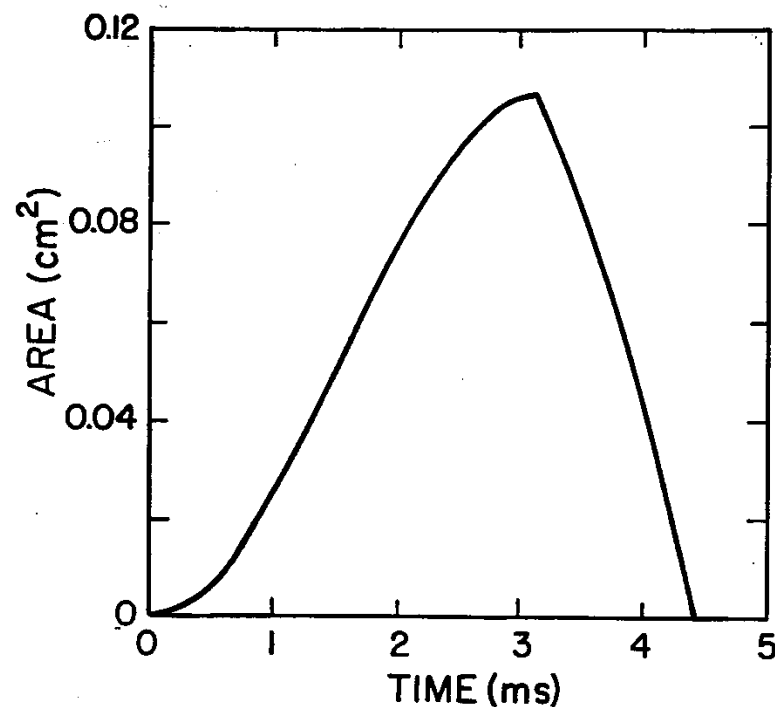
Interaction fluide-parois : vibrations

Vibration des cordes vocales : Voisement

Stevens (1998)

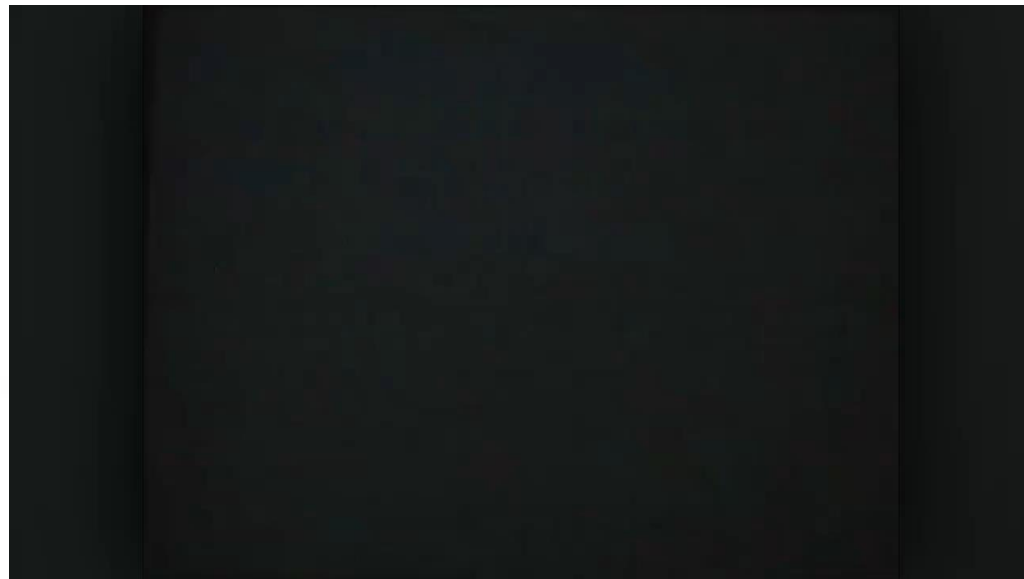
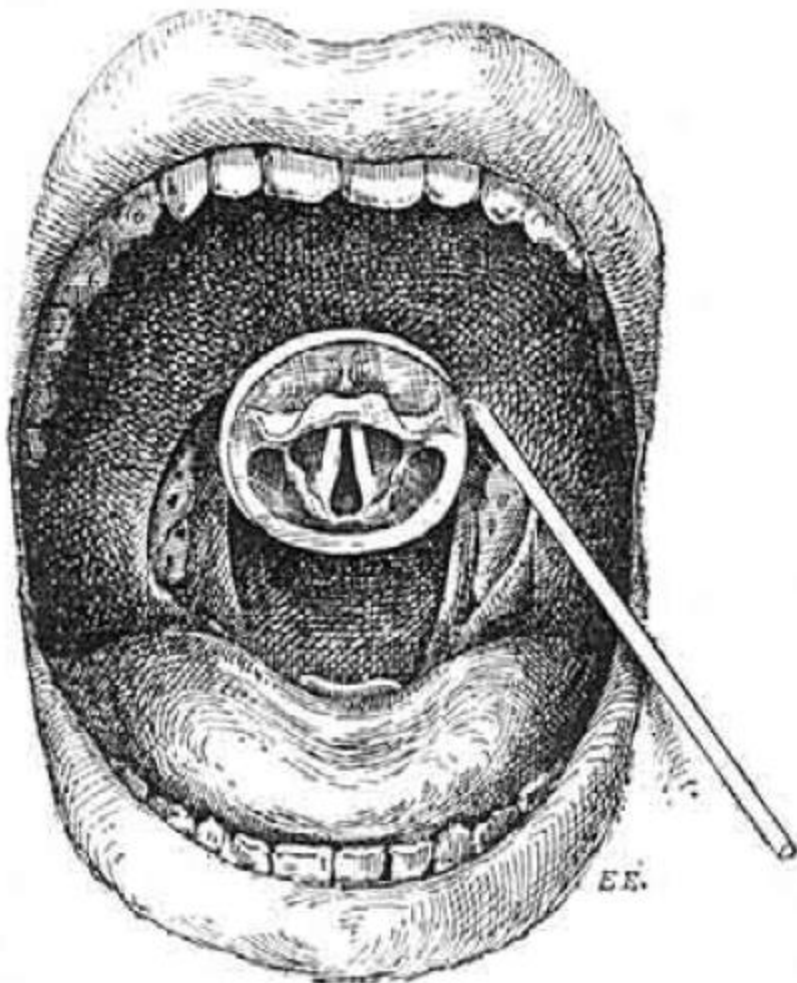


Mouvement des parties inférieures et supérieures



Aire à la glotte

Endoscopie : Méthode



Transillumination



Electroglottographie (EGG) – Impédance du larynx

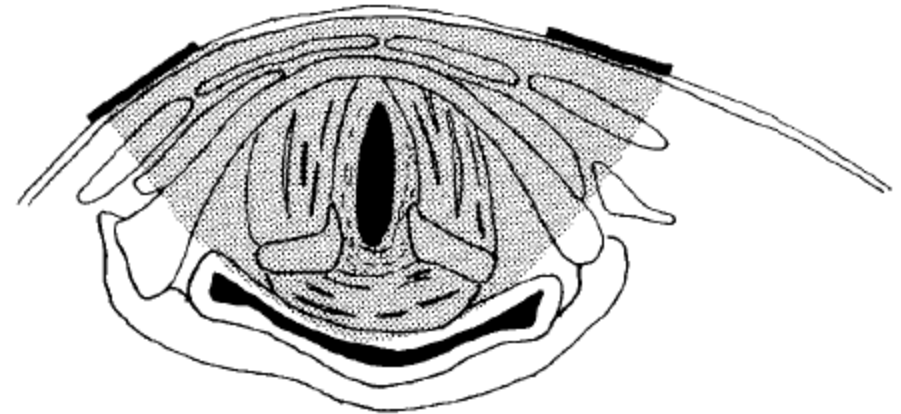


FIG. 1. The larynx in its anatomic environment. Superficial black rectangles represent electrodes on the skin. Gray shading suggests the cross-sectional region through which electric current flows.

Baken, R.J., Journal of Voice, 1992

Electroglottographie – Impédance du larynx

Variation de l'impédance

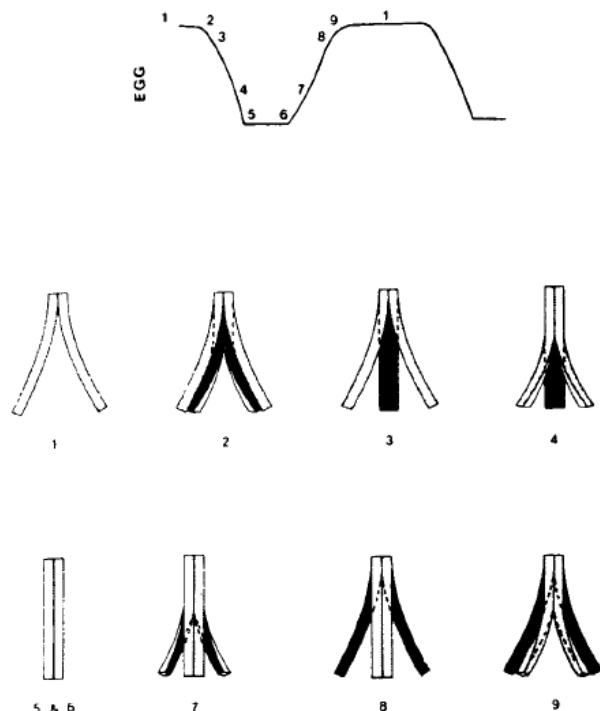
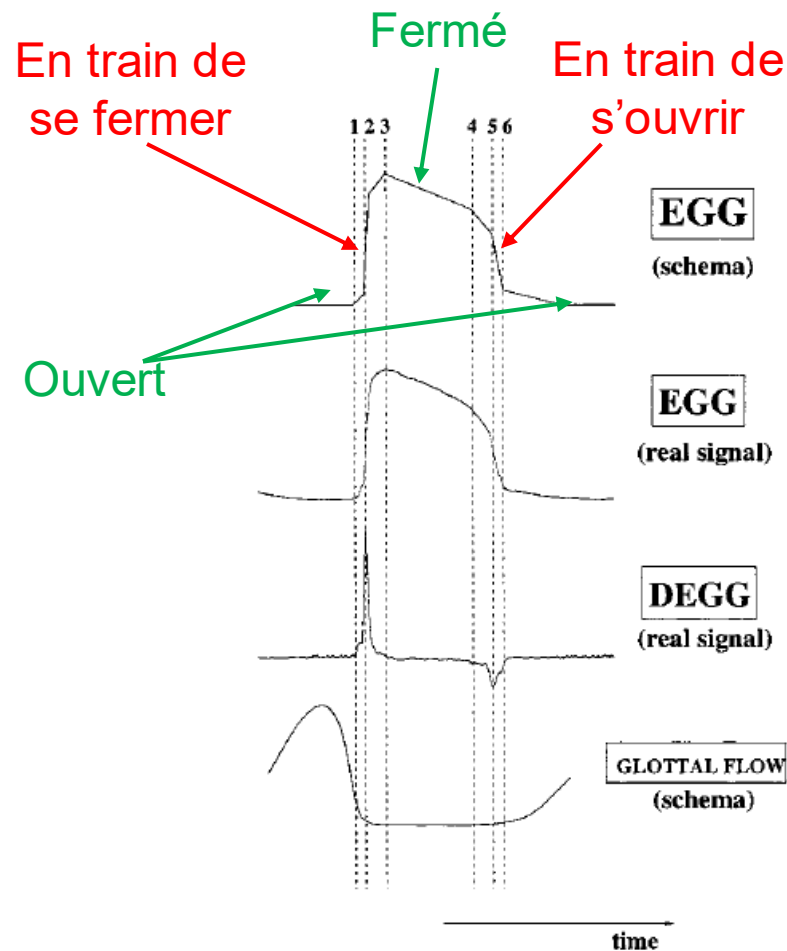


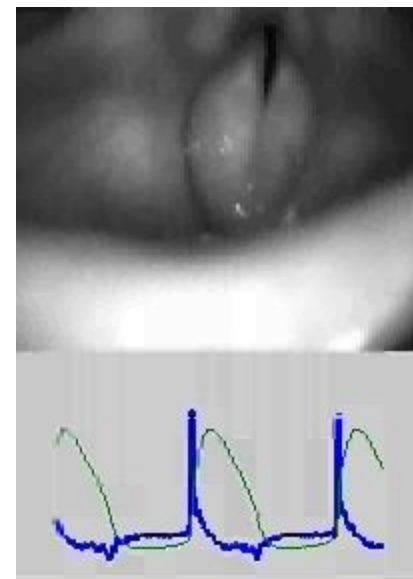
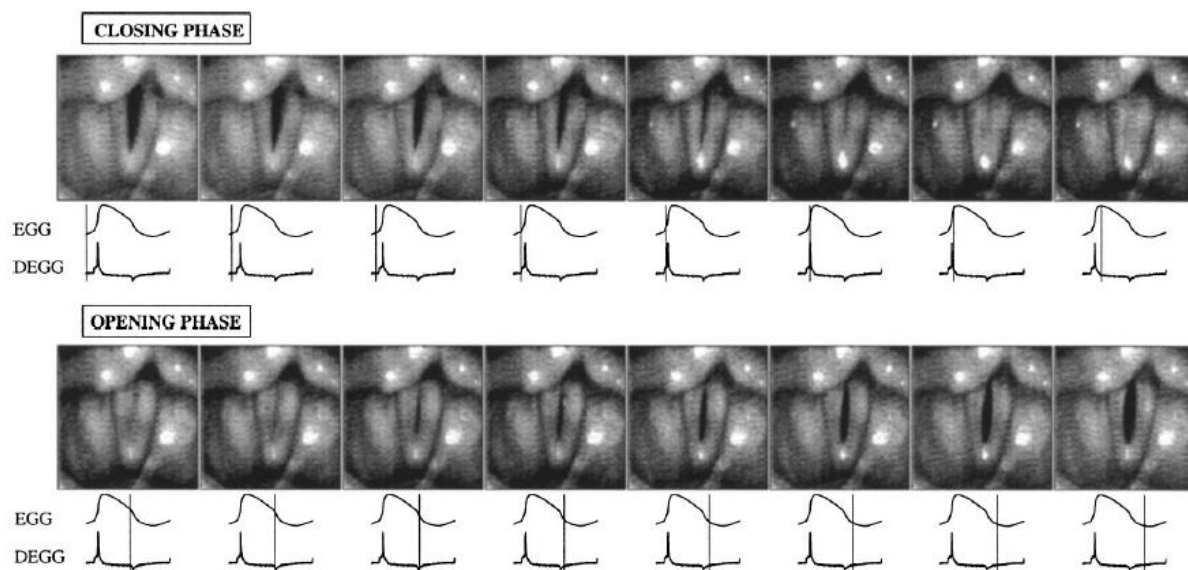
FIG. 8. Geometric two-mass model of the vocal fold activity underlying features in the Lx wave. Note that the Lx wave at the top of the figure is oriented with increasing vocal fold contact (decreasing trans-neck impedance) *downward*. White areas represent the upper mass of the vocal fold, black areas the lower mass. 1: both masses open; 2: upper open, lower ½ closed; 3: upper open, lower closed; 4: upper ½ closed, lower closed; 5 and 6: both closed; 7: upper closed, lower ½ open; 8: upper closed, lower open; 9: upper ½ open, lower open. Reprinted with permission (38).



Baken, R.J., Journal of Voice, 1992

Henrich, N. et al. JASA, 2004

Electroglottographie - Mesures

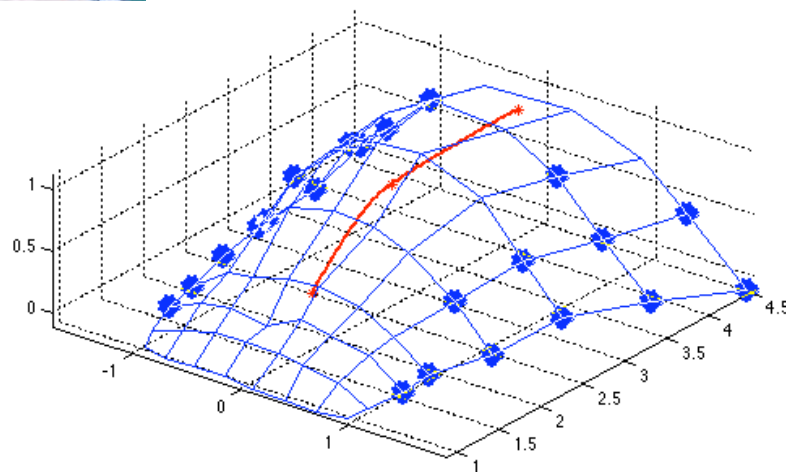


Henrich, N. et al. JASA, 2004

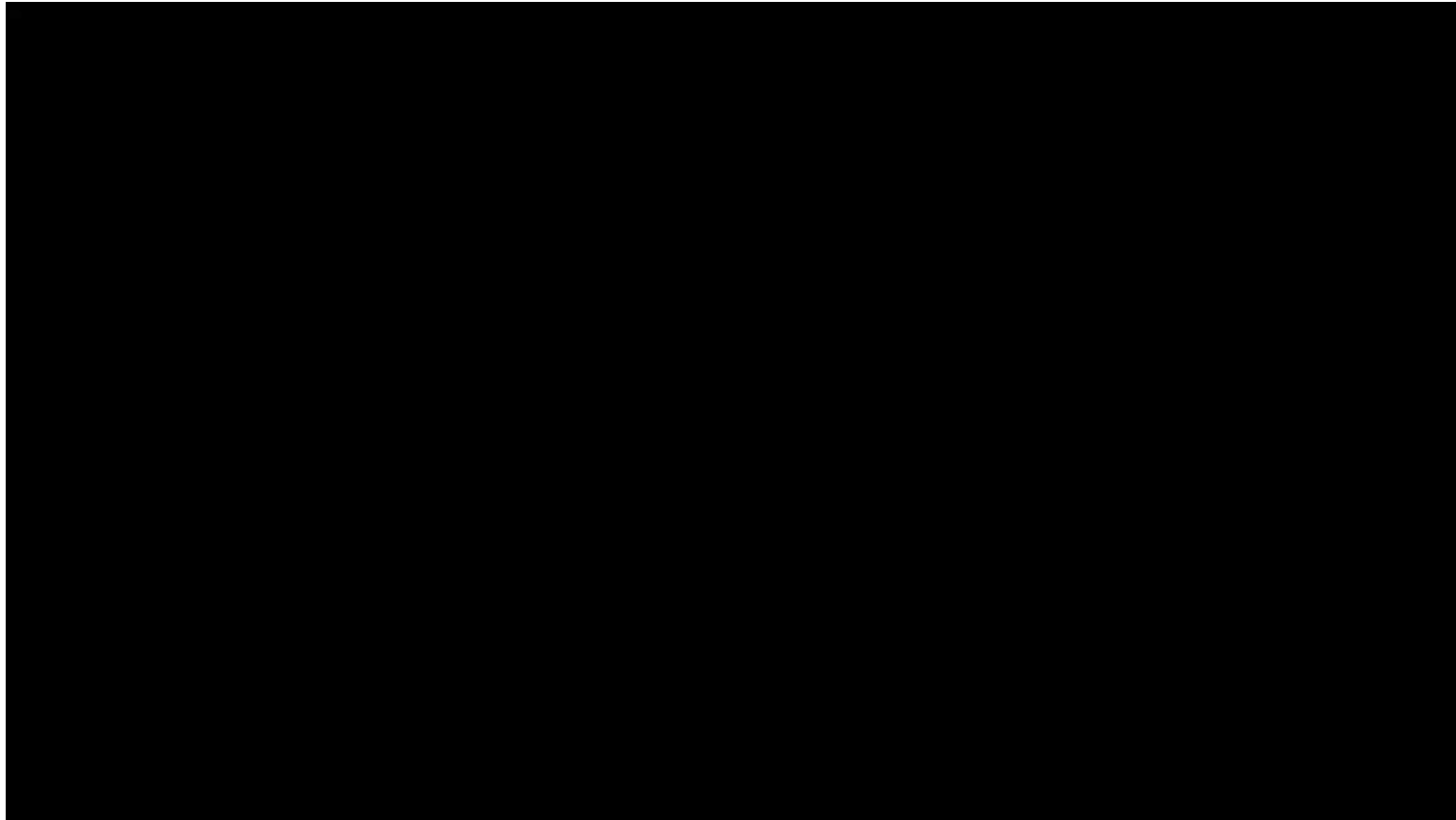
Mesures des contacts

Electropalatographie-Electropalatography

Electropalatographie



Electropalatographie



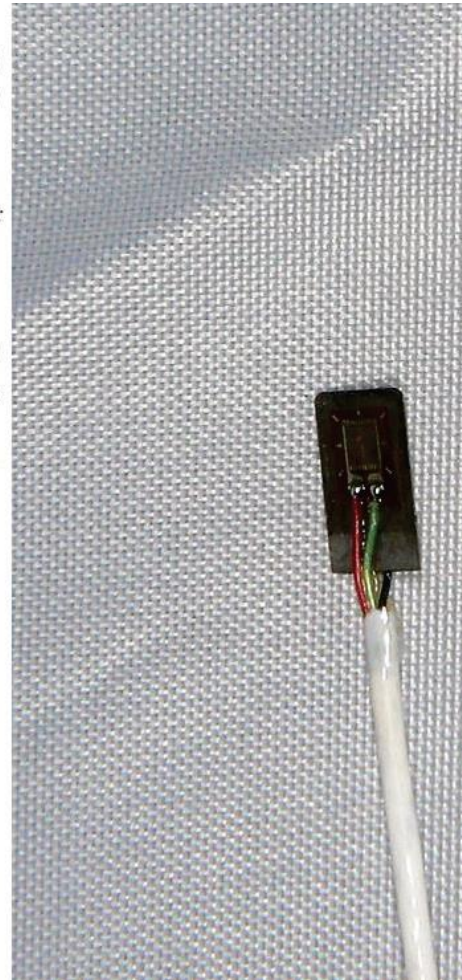
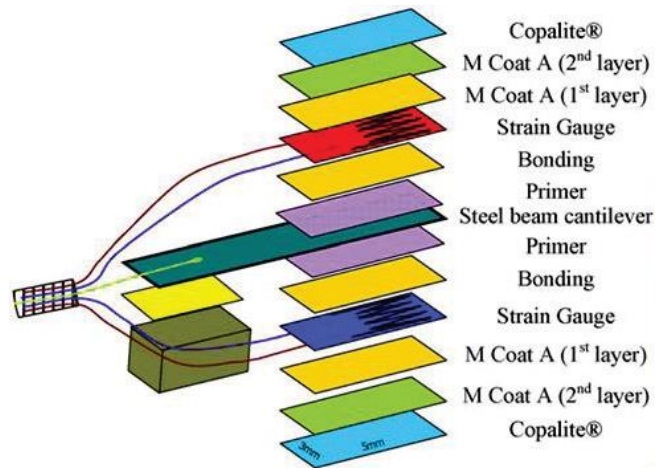
Mesures dynamiques

Capteurs de forces

Capteurs de force

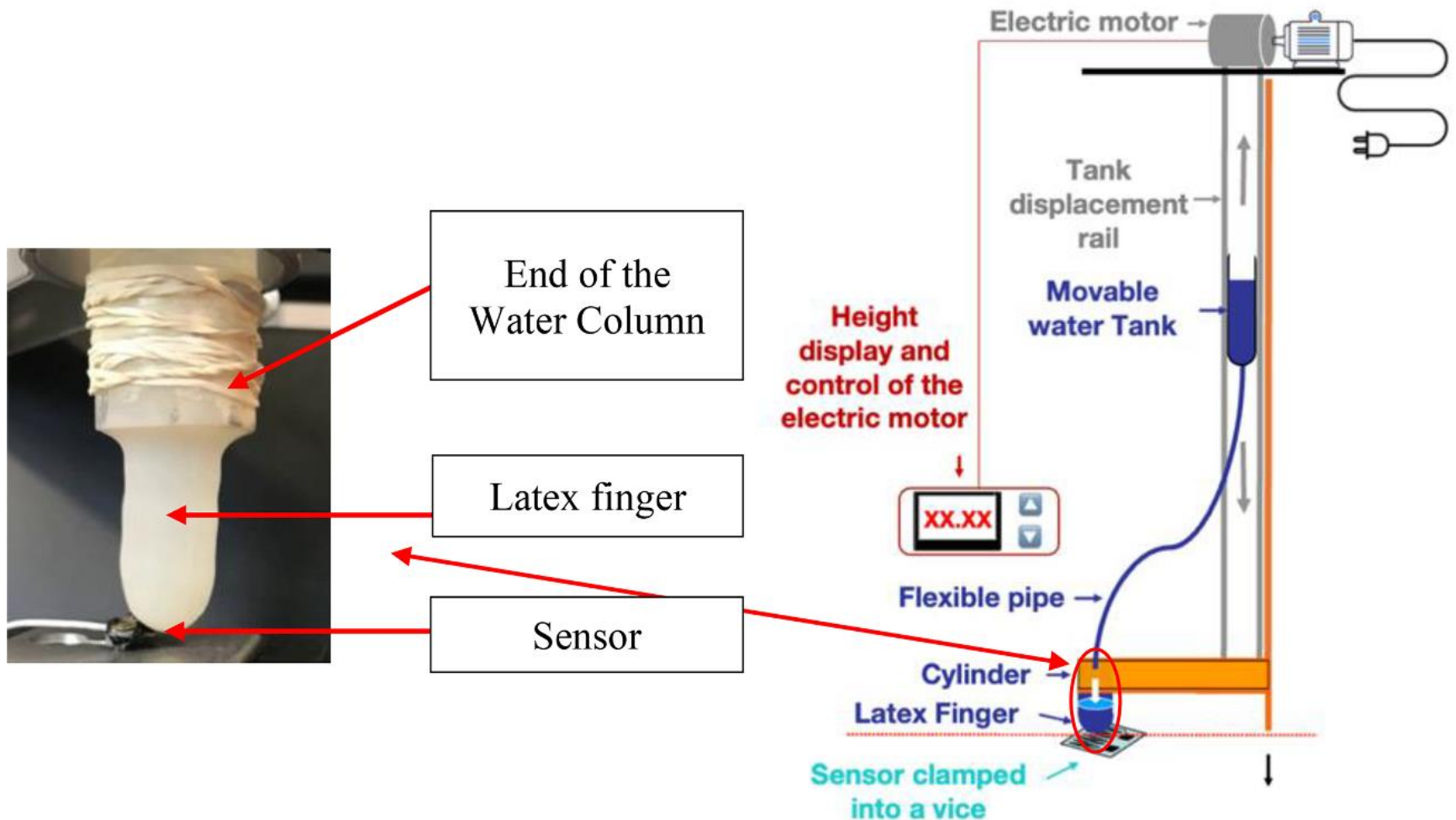


Capteurs de force : jauge de contrainte



Capteurs de force : calibration

Jeannin & Perrier, 2023



Capteurs de force : mesures

Mirchandani et al., 2020

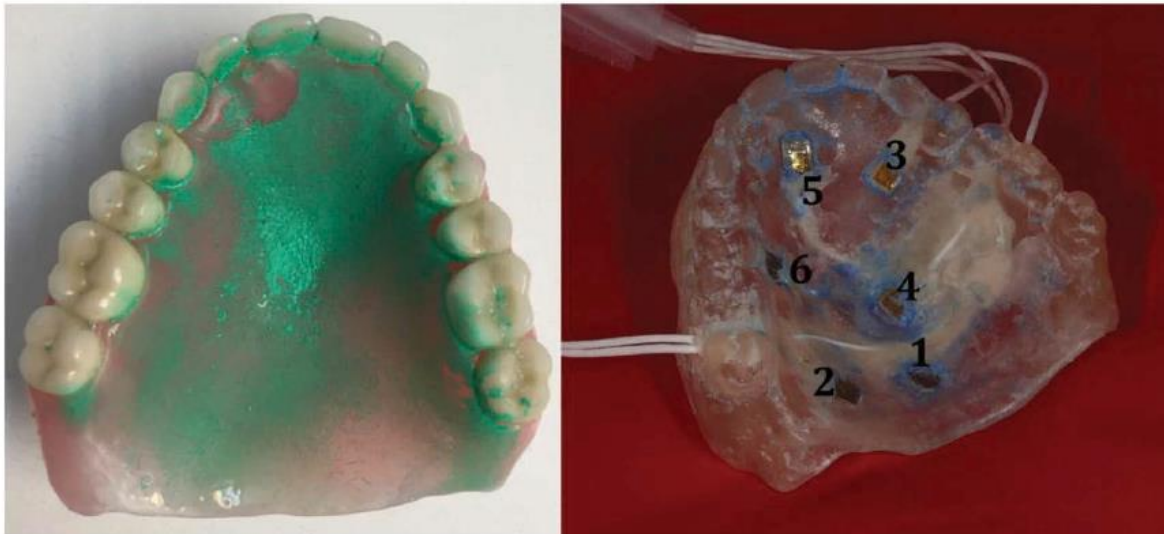


Figure 2. Left panel: palatogram for /ita/ on a of the complete denture; the replica was initially covered with green powder; as the tongue touched it, the powder was removed in the region where contact occurred; thus, the palatogram informs about the location where strain gauge sensors have to be inserted, in order to measure the tongue-to-palate pressure. Right panel: Location of the six strain gauge sensors in the replica of the complete denture, as determined from the palatograms for this subject.

Capteurs de force : mesures

Mirchandani et al., 2020

Consonne alvéolaire /t/

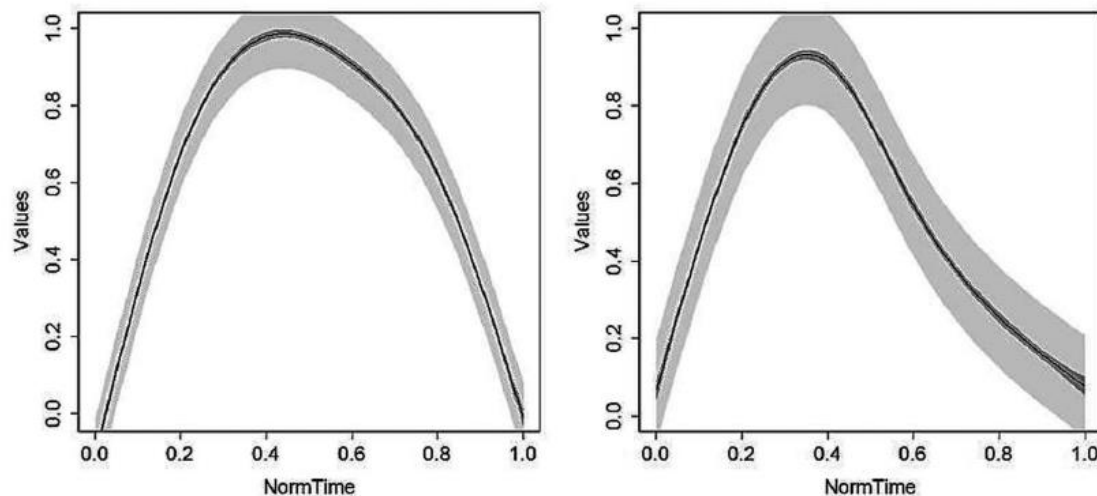


Figure 6. Pressure time patterns for /t/ in /ita/ normalized in time and in amplitude. Dark grey shaded region: 95% confidence interval; light grey shaded region: prediction interval at one standard deviation. Left panel: Sensor 5. Right panel: Sensor 6.

Capteurs de force : mesures

Mirchandani et al., 2020

Consonne vélaire /k/

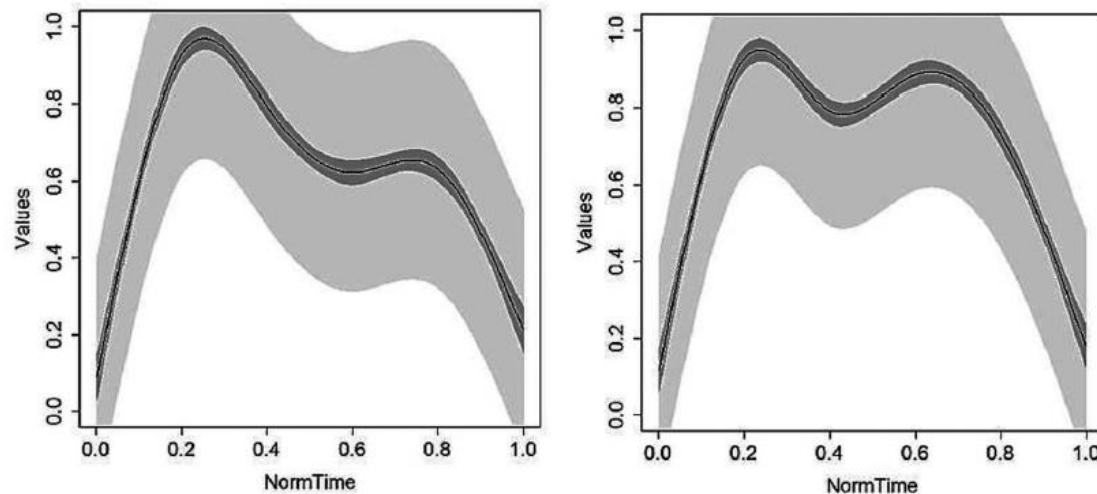
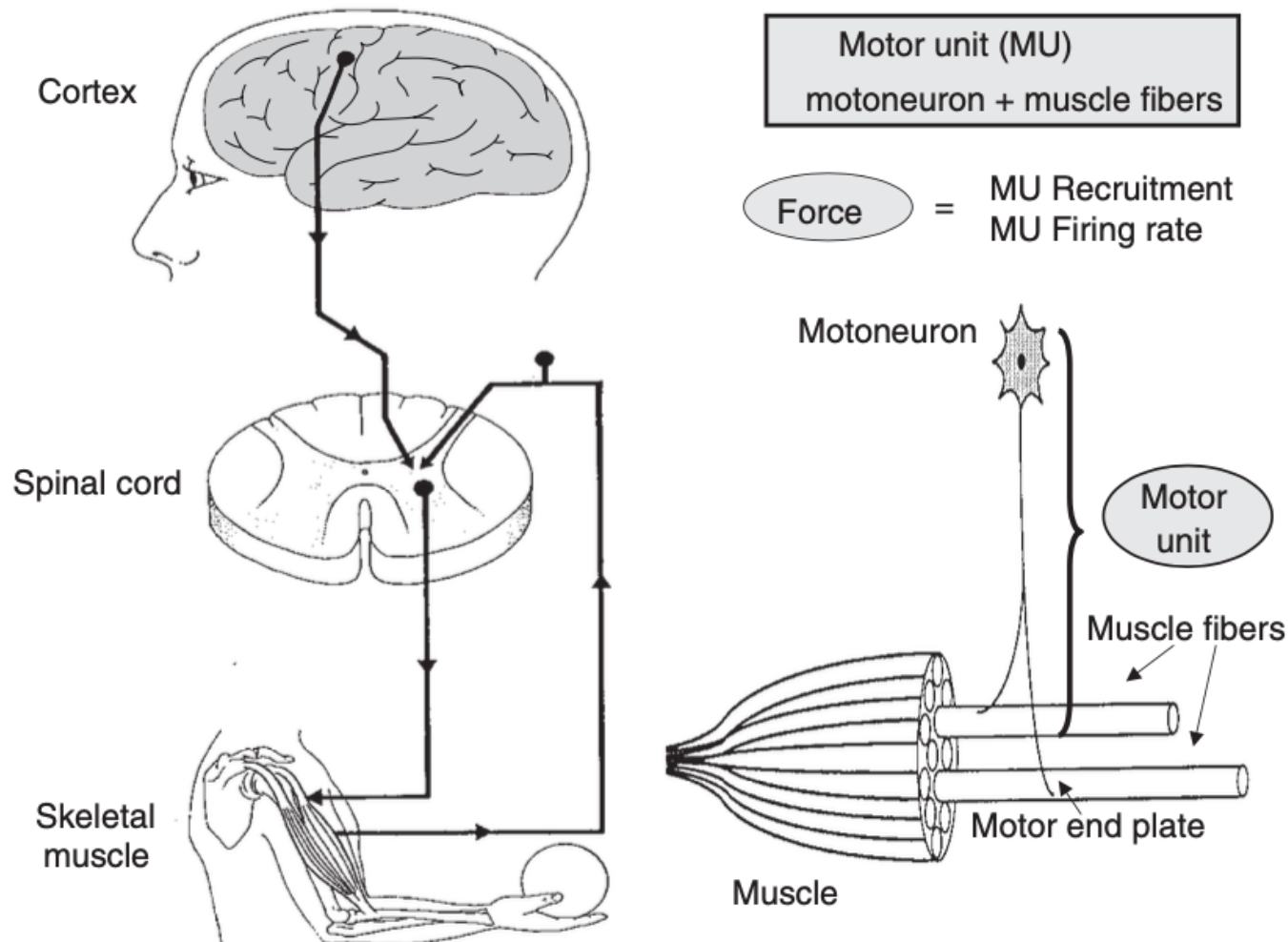


Figure 7. Pressure time patterns for /k/ in /ika/ normalized time and in amplitude. Dark grey shaded in time and in amplitude. Dark grey shaded region: 95% confidence interval; light grey shaded region: prediction interval at one standard deviation. Left panel: Sensor 1. Right panel: Sensor 2.

Mesures dynamiques

Electromyographie

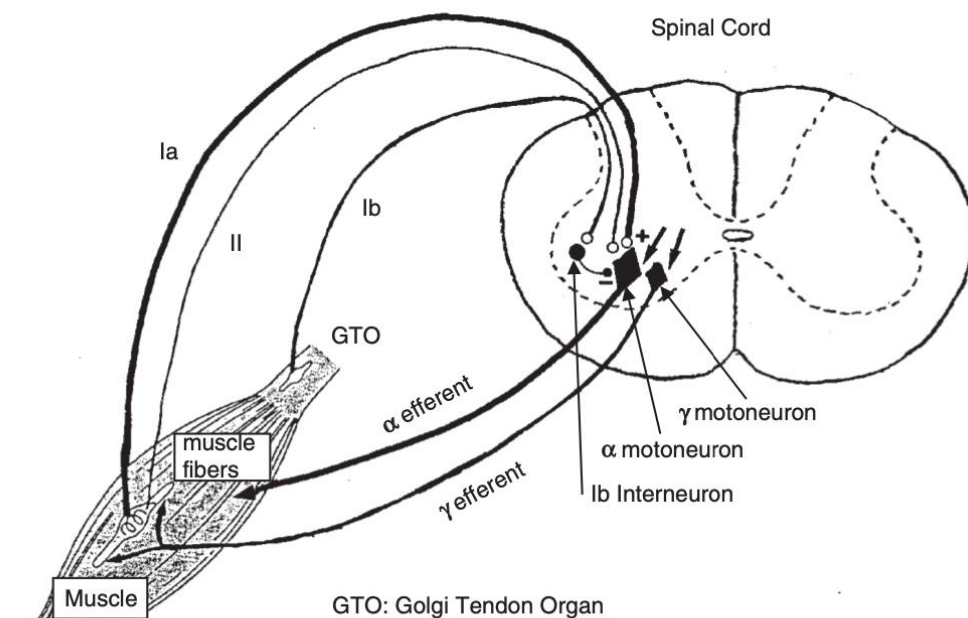
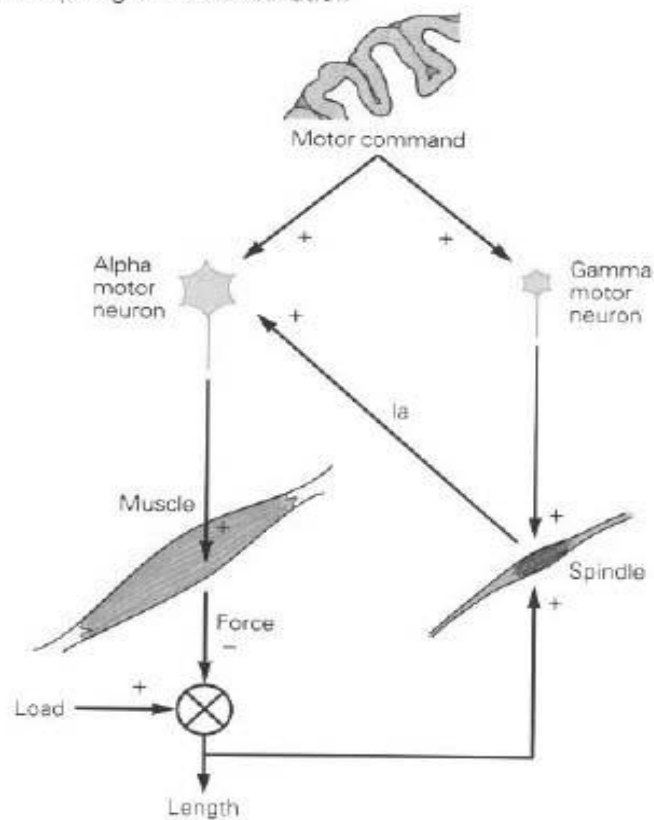
Electromyographie - Principes



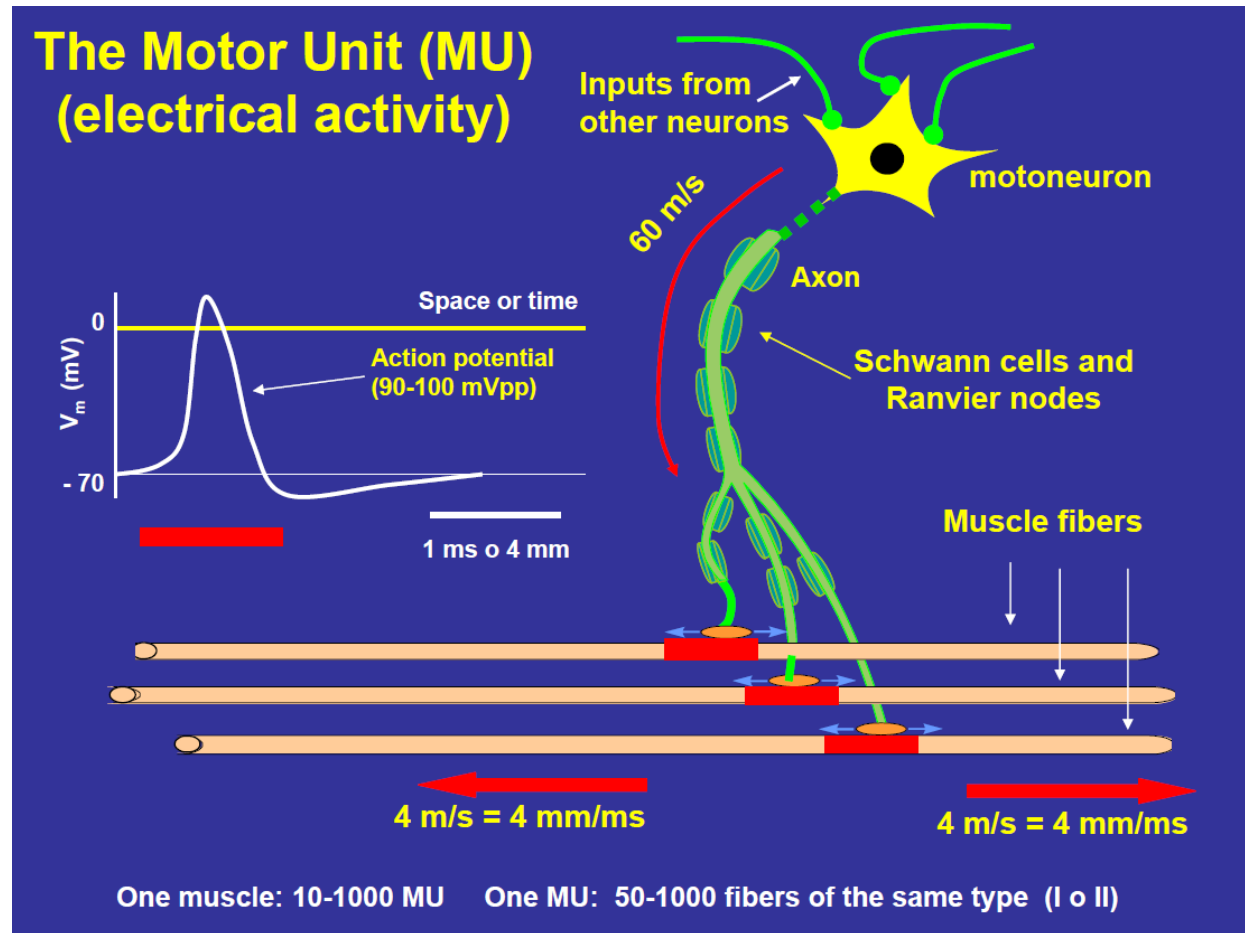
Merletti, R. & Parker, P. (2004). Wiley-Interscience

Electromyographie - Principes

A Alpha-gamma coactivation



Electromyographie - Principes



Merletti, R. (2006) - Slovenian-Italian Workshop on Quantitative Needle and High Resolution Surface EMG December 4, 2006

Electromyographie - Principes

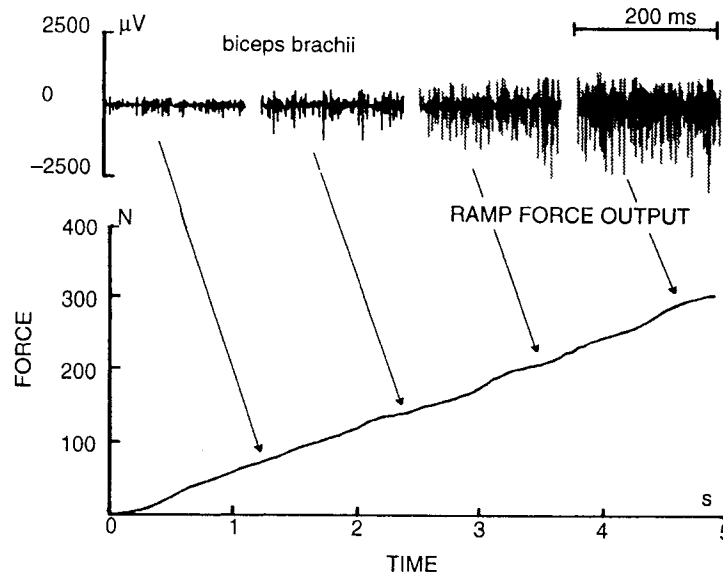
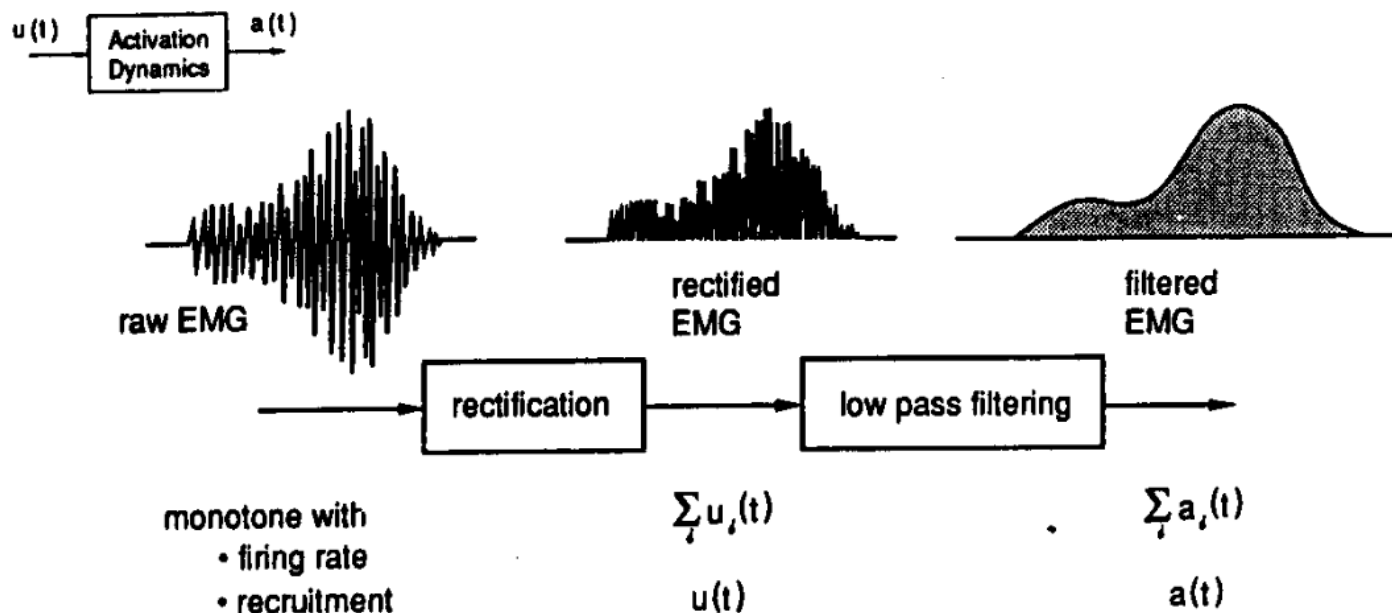


Figure 1.6. Intramuscular spike recordings obtained from the biceps brachii muscle during linearly force-varying isometric muscle contraction.

Merletti, R. & Parker, P. (2004). Wiley-Interscience

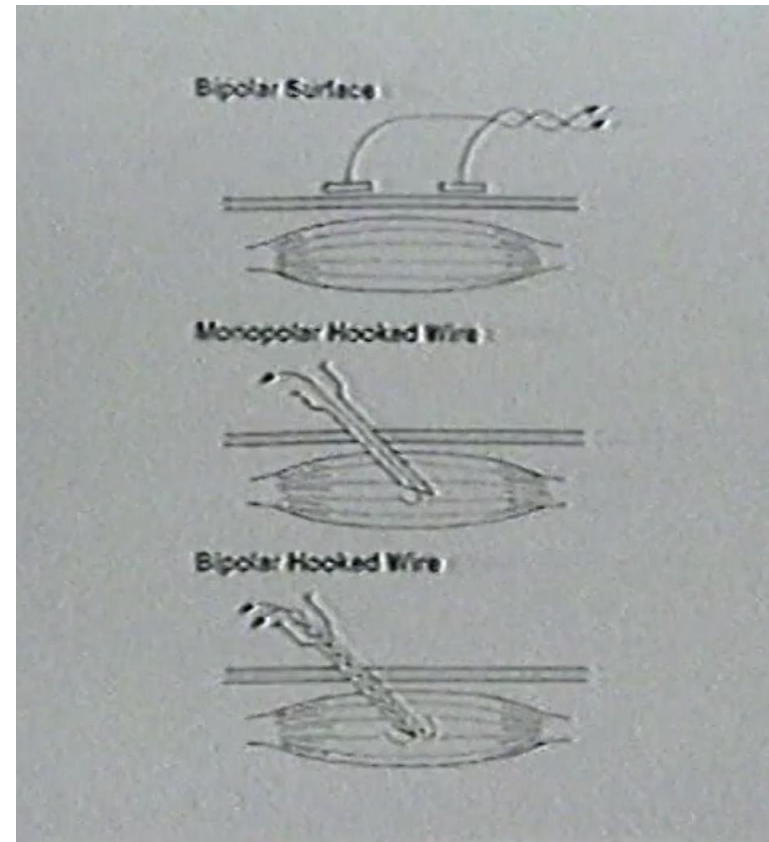
Electromyographie - Principes



Zajac FE (1989). Crit Rev in Biomed Eng

Electromyographie - Méthode

Kiyoshi Oshima
Katherine S. Harris
Fredericka Bell-Berti

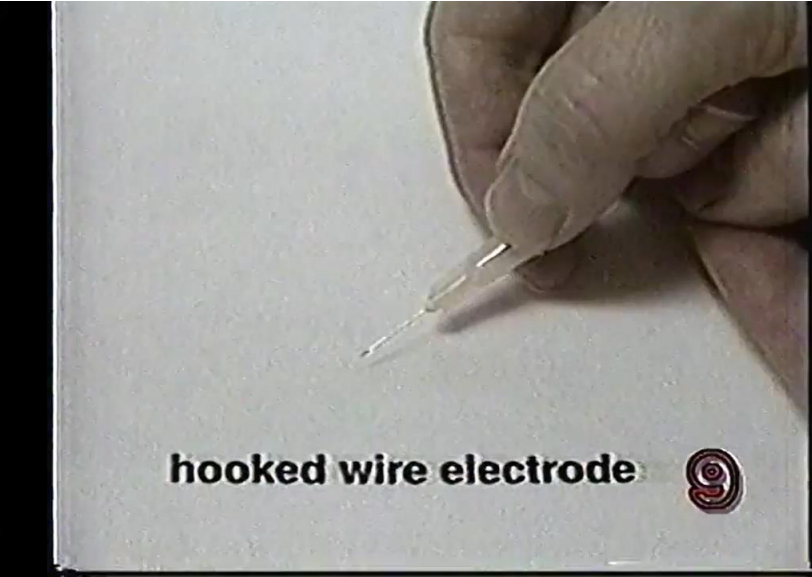


Electromyographie - Méthode

Electromyographie à l'aiguille



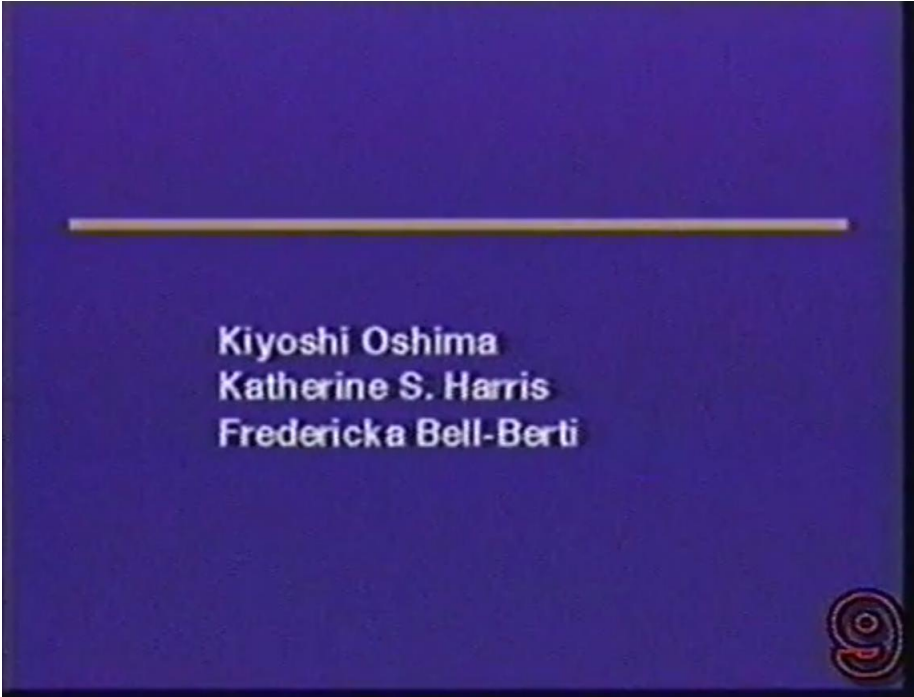
Kiyoshi Oshima
Katherine S. Harris
Fredericka Bell-Berti



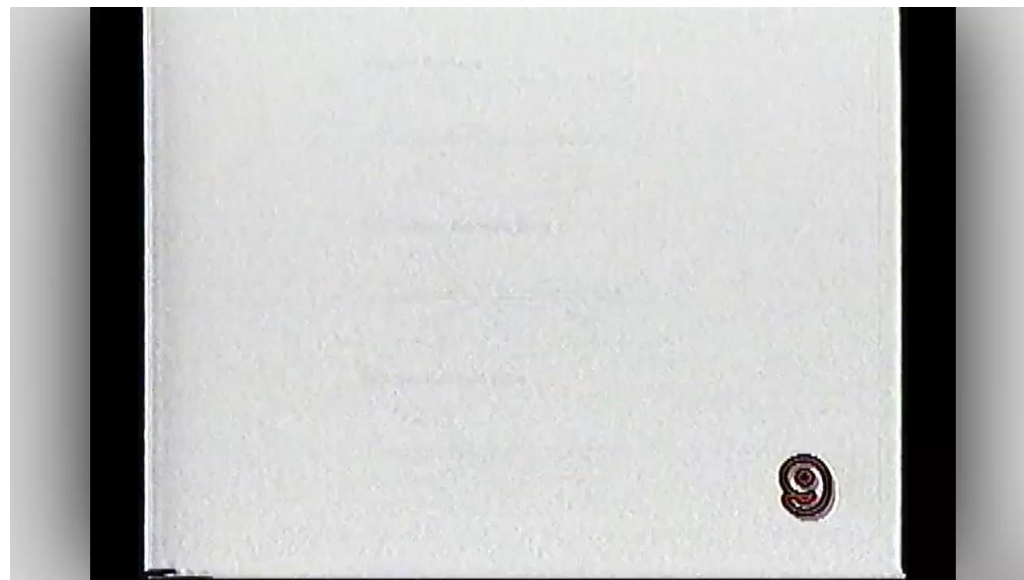
hooked wire electrode

Electromyographie - Méthode

Electromyographie de surface



Kiyoshi Oshima
Katherine S. Harris
Fredericka Bell-Berti



Electromyographie - Méthode

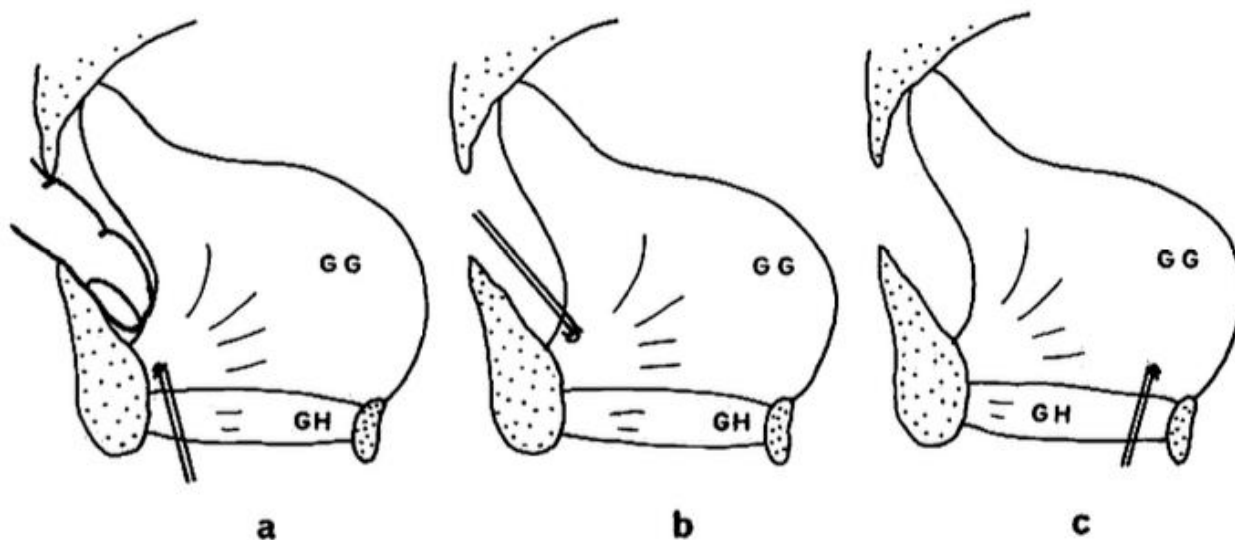


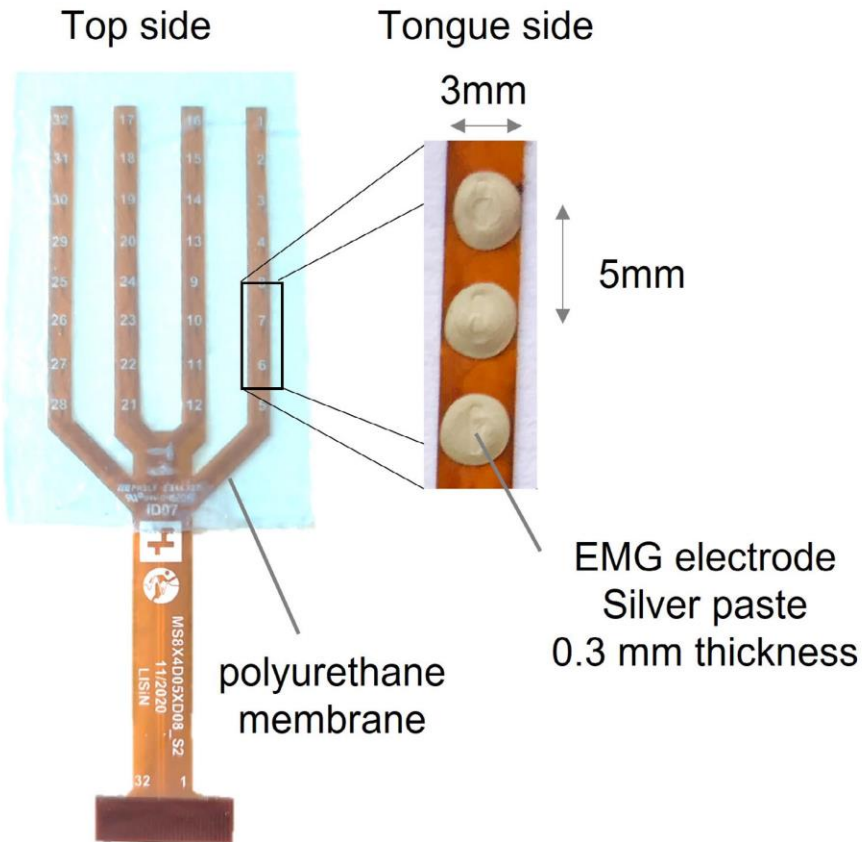
Fig. 6-a,b Insertion of the electrodes in the anterior portion of the genioglossus muscle.

Fig. 6-c Insertion of the electrodes in the posterior portion of the genioglossus muscle.

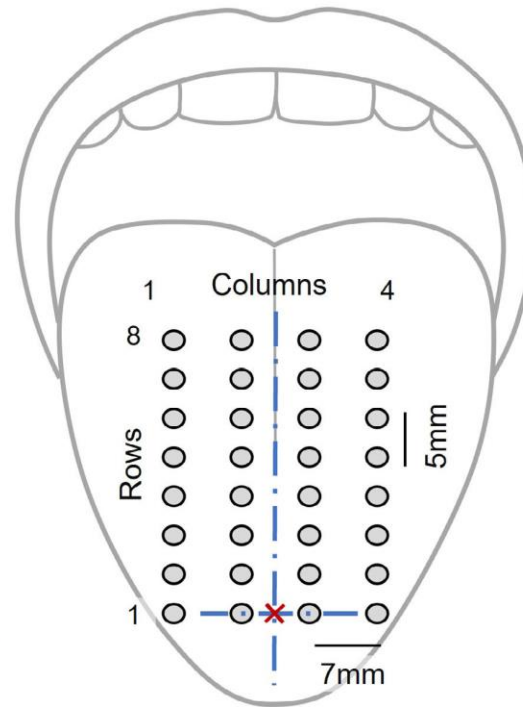
Miyawaki, et al Ann Bull RILP, 9, 91-106, 1975

Electromyographie – Nappes d'électrodes

a)



b)



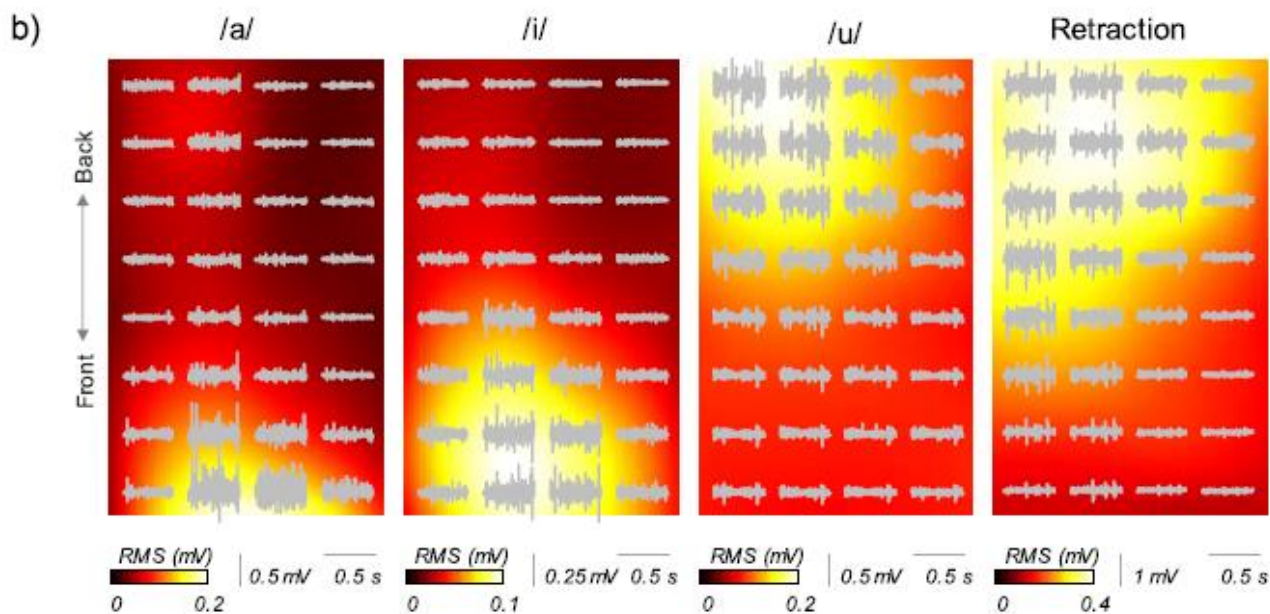
c)



HDEMG amplifier

Botter et al., IEEE TRANS. ON NEURAL SYSTEMS AND REHABILITATION ENG., 2024

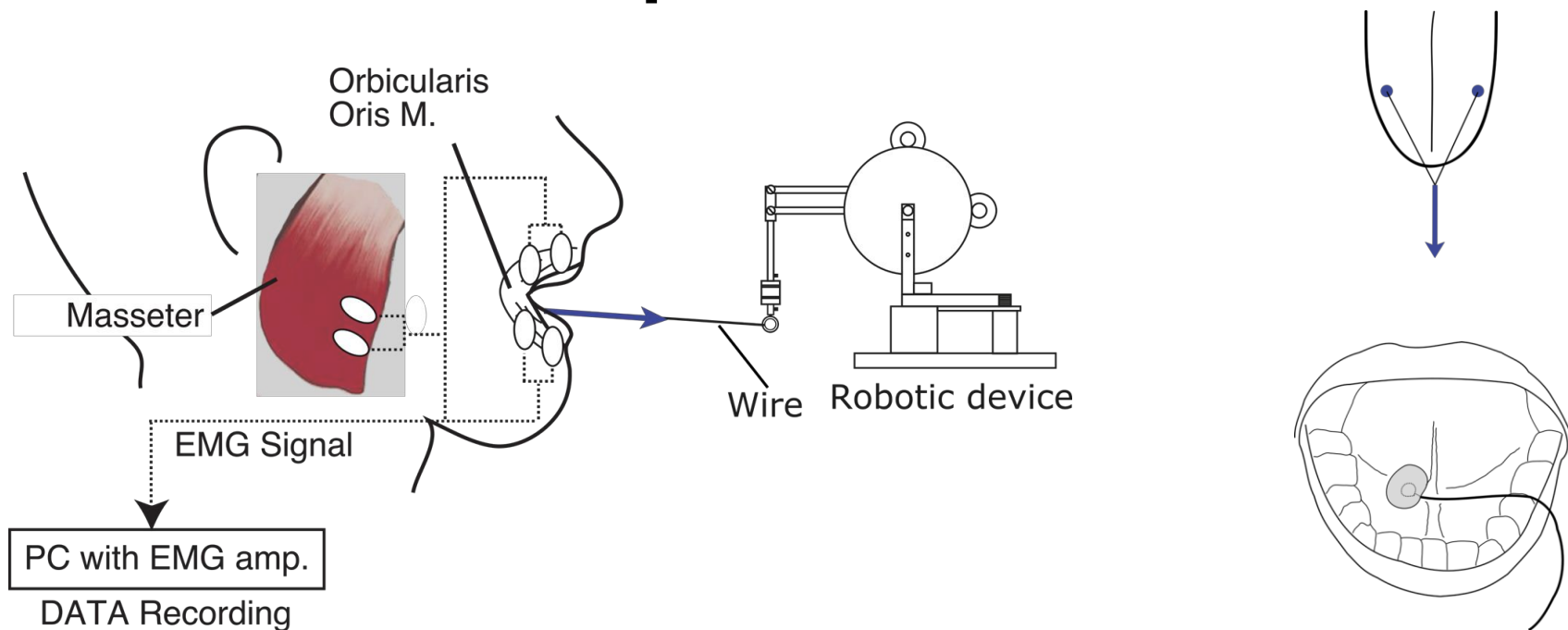
Electromyographie – Nappes d'électrodes



Botter et al., IEEE TRANS. ON NEURAL SYSTEMS AND REHABILITATION ENG., 2024

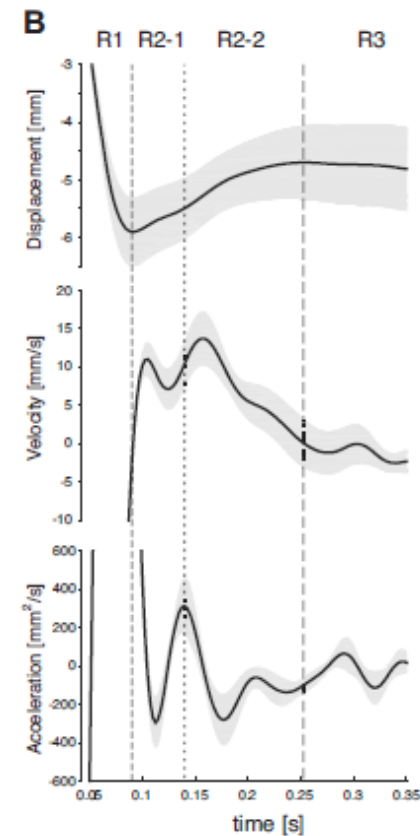
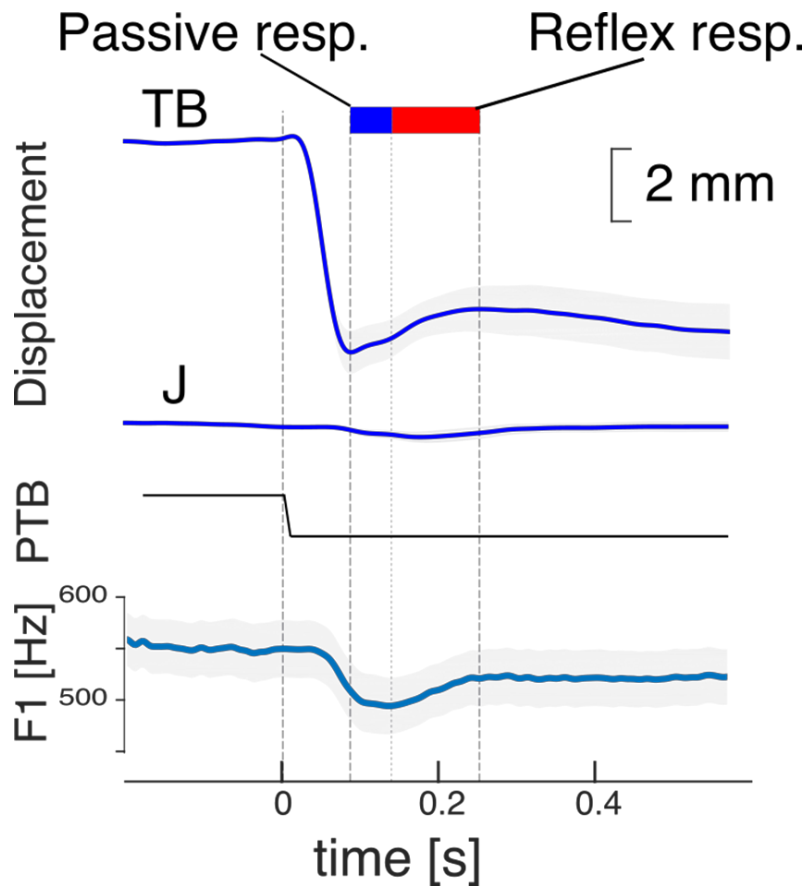
Exemples de paradigmes expérimentaux

Exploiter une perturbation pour connaître le rôle du réflexe proprioceptif dans le contrôle de la parole.



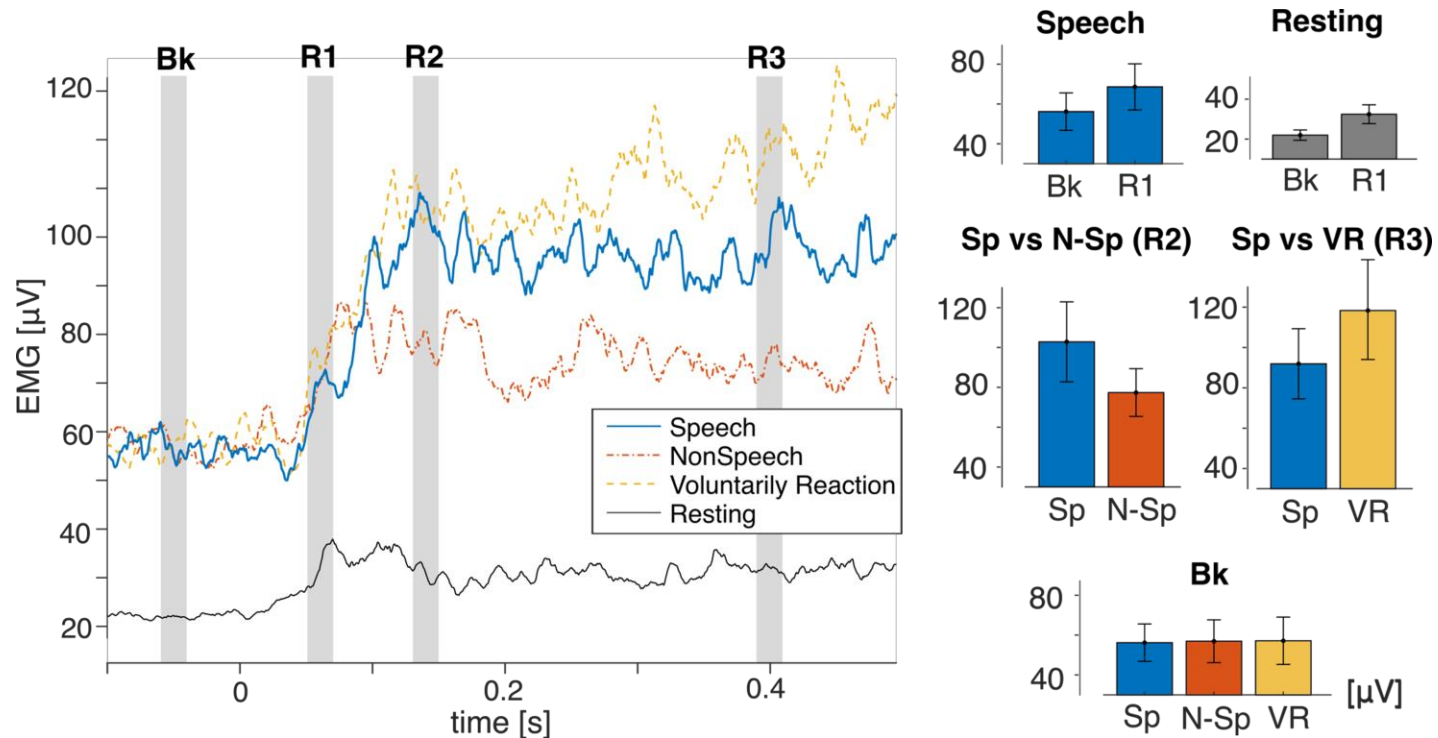
Ito, Bouguerra, Bourhis, Perrier, Scientific Reports, 2024,

Observation cinématique



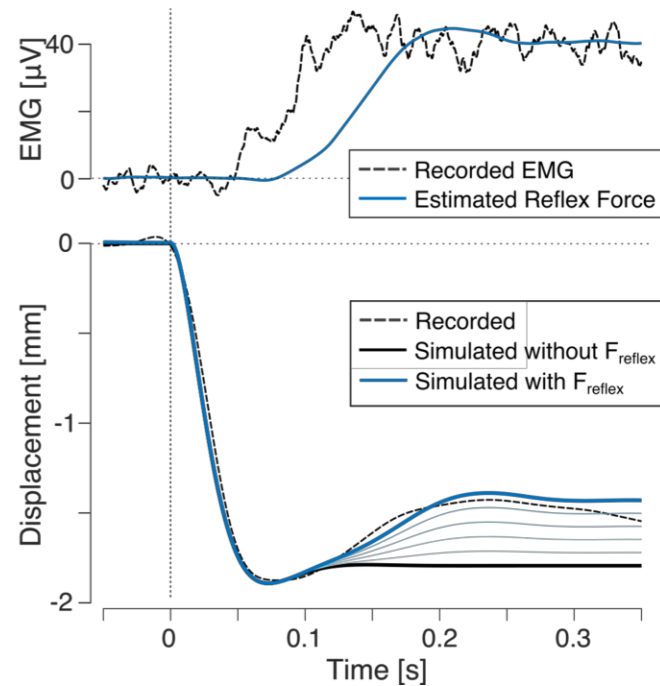
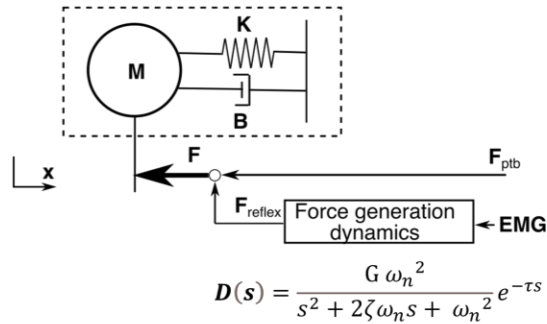
Ito, Bouguerra, Bourhis, Perrier, Scientific Reports, 2024,

Observation EMG



Ito, Bouguerra, Bourhis, Perrier, Scientific Reports, 2024,

Modélisation



Ito, Bouguerra, Bourhis, Perrier, Scientific Reports, 2024,